

Jet Propulsion Laboratory
California Institute of Technology

VSWIR L1 & L2: Radiance and Reflectance Algorithm Maturity, Calibration, and Validation

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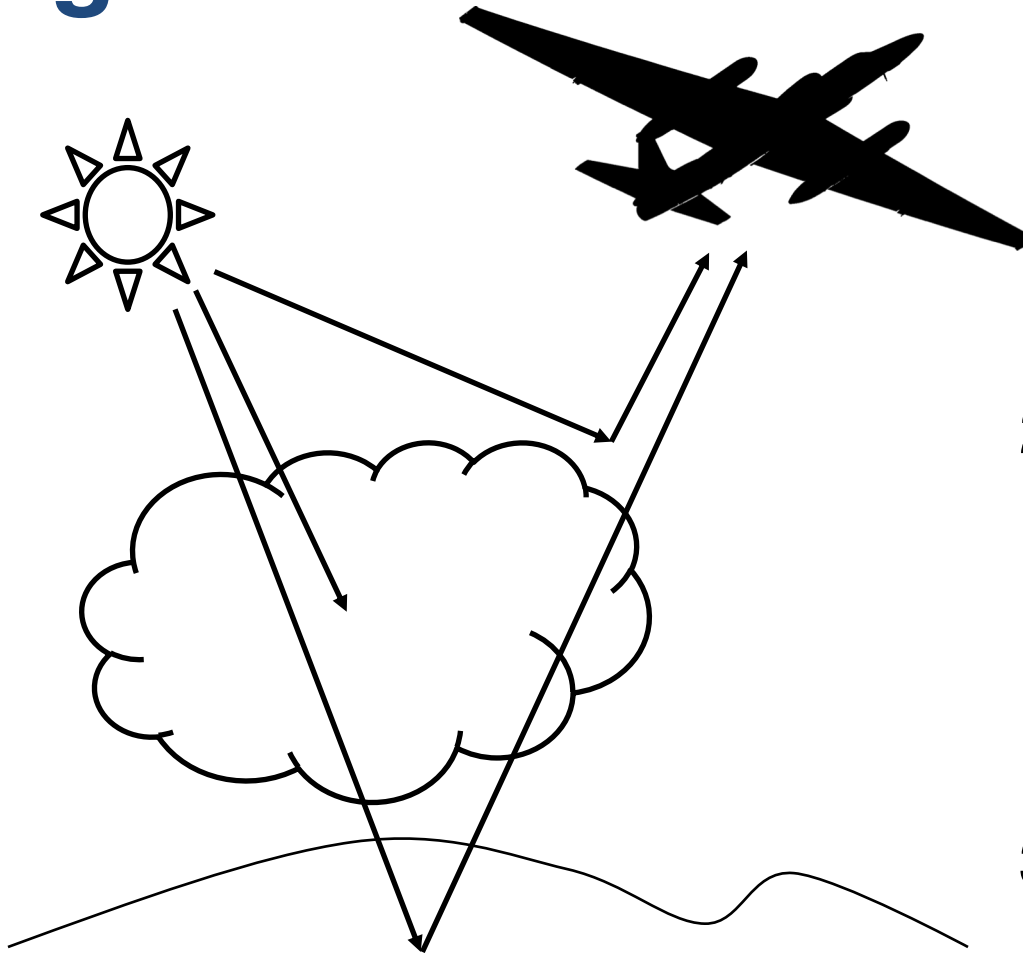
²Naval Research Laboratory

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Agenda



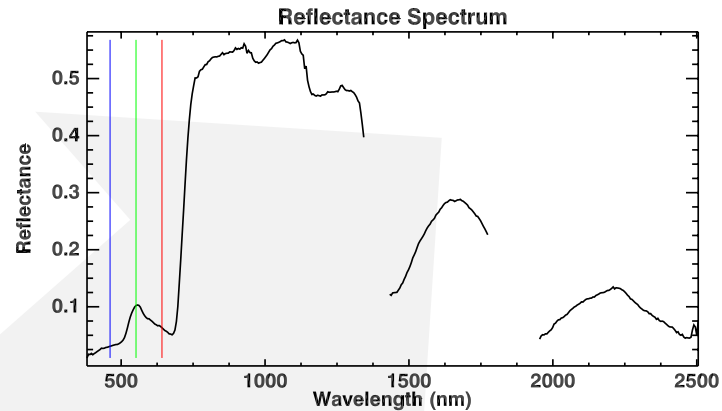
1. Instrument calibration: radiometric and spectral
2. Estimation of atmosphere and surface properties
3. Field validation methods and results



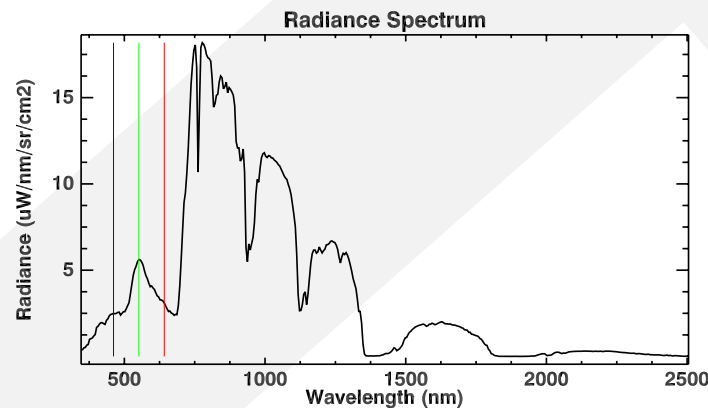
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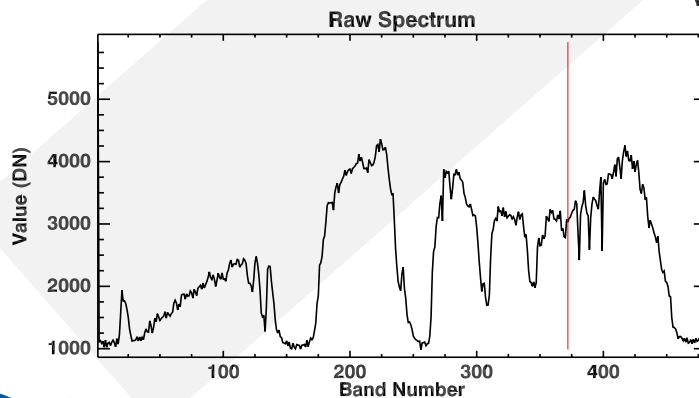
Typical Analysis Chain



Lambertian
Reflectance
(HDRF)



Radiance at
sensor
 $\text{mW}/\text{nm}/\text{cm}^2/\text{sr}$



Raw Digital
Numbers

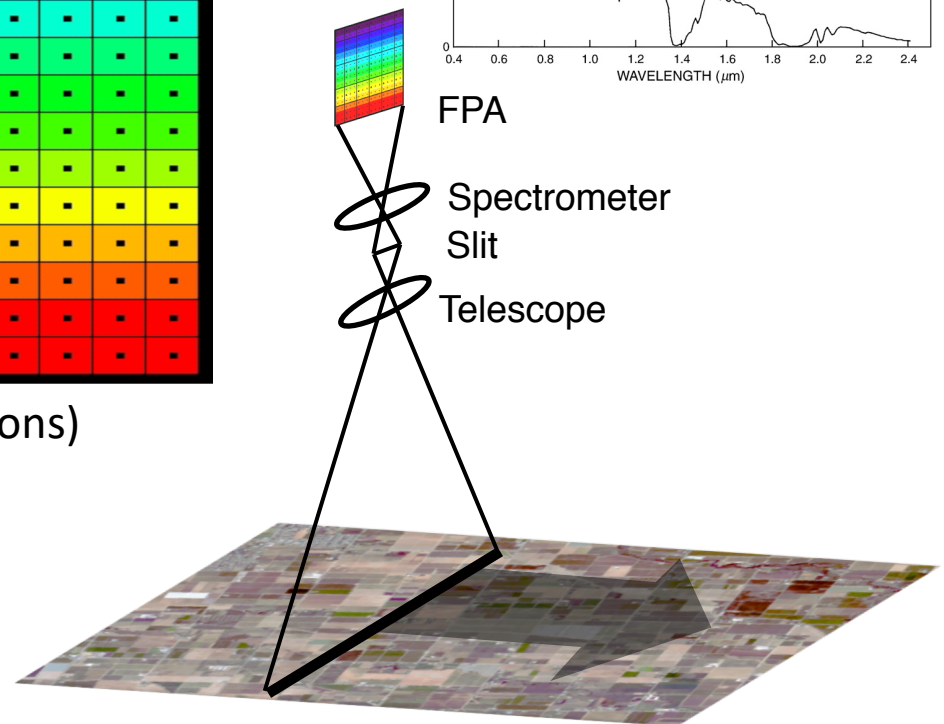
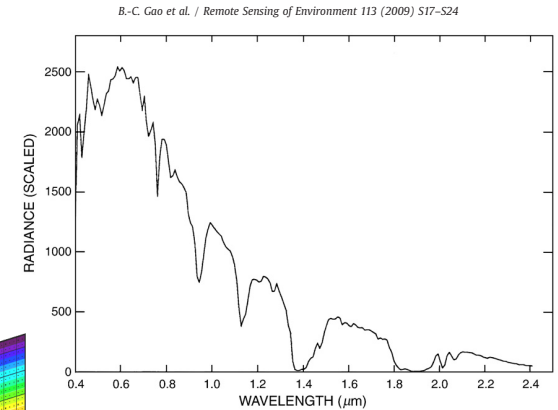
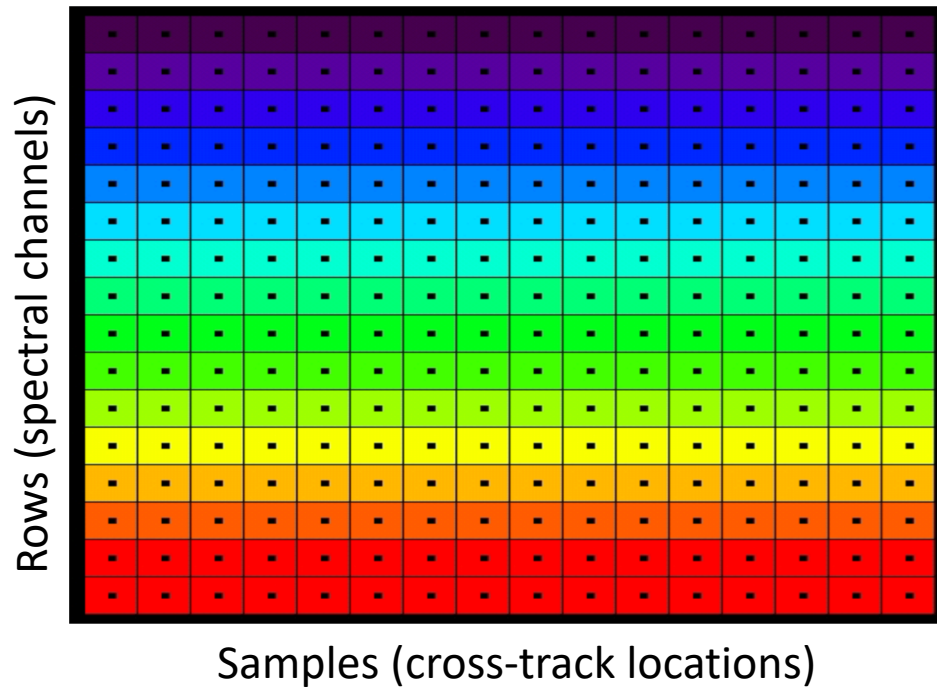
[Gao et al., 1993;
Green et al., 1998,
Thompson et al., 2015]



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Calibration Conventions

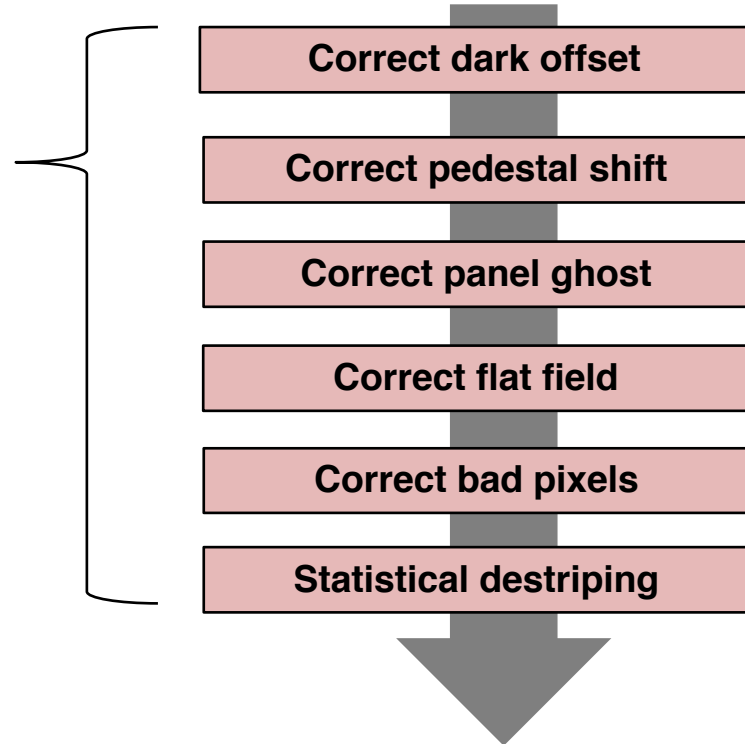


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Working backwards from the FPA

1. **Electronic effects** - the time-dependent radiometric response of each detector



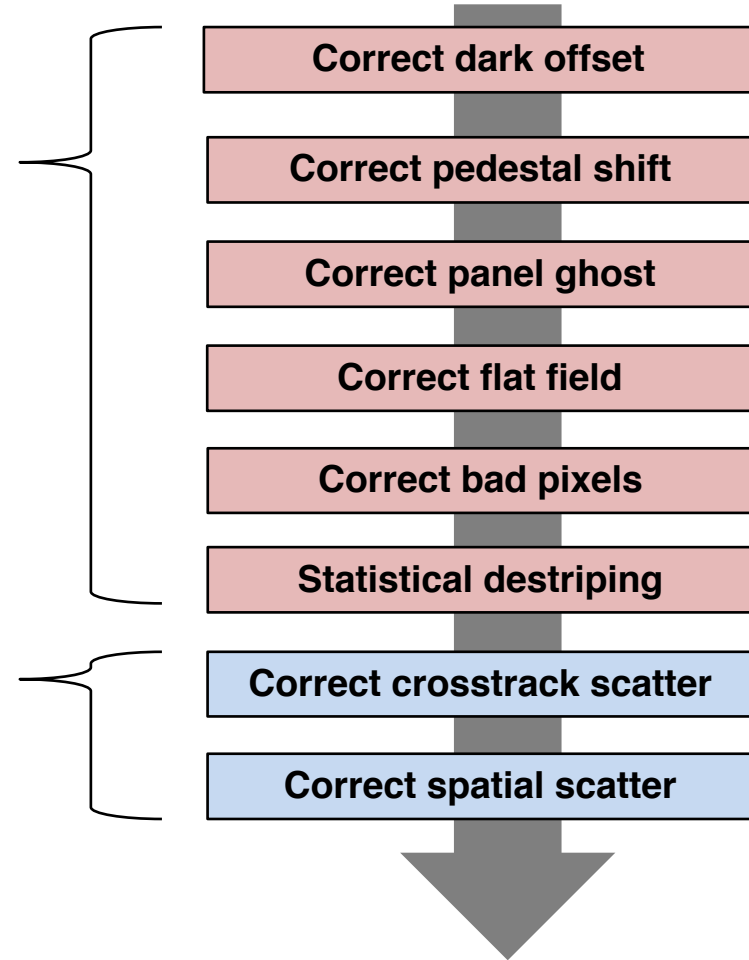
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Working backwards from the FPA

1. **Electronic effects** - the time-dependent radiometric response of each detector

2. **Optical effects** - the spatial and spectral “view” of each detector

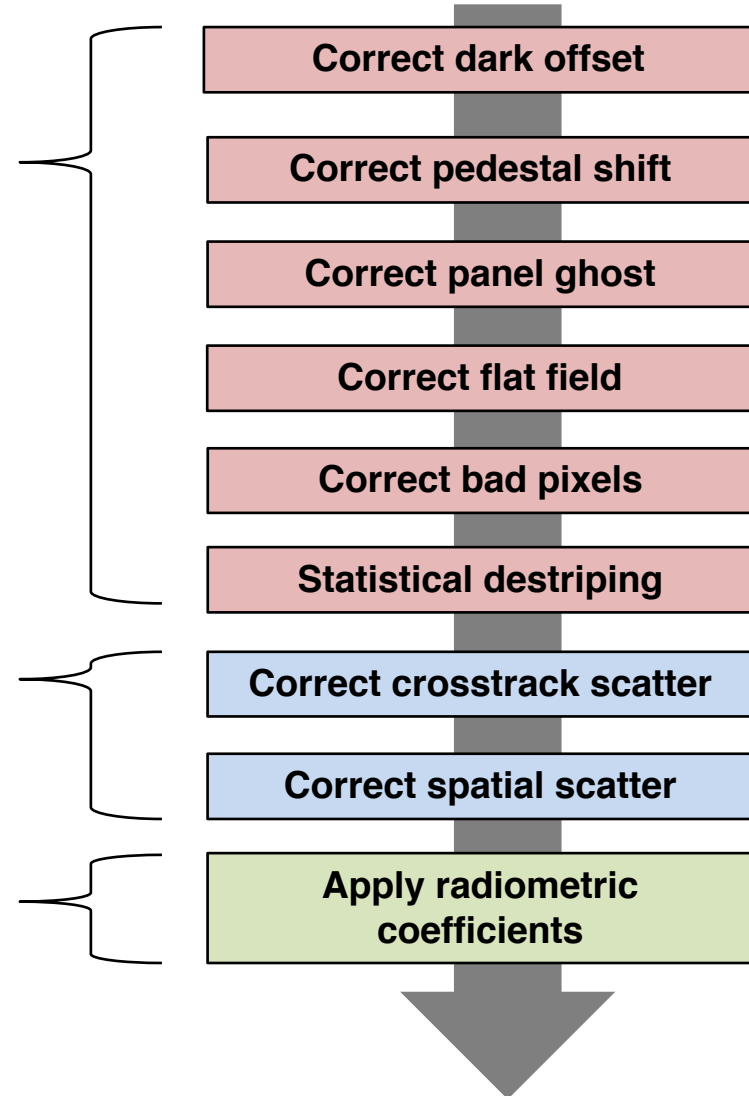


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Working backwards from the FPA

1. **Electronic effects** - the time-dependent radiometric response of each detector
2. **Optical effects** - the spatial and spectral “view” of each detector
3. **Calibration to the S.I.** (absolute spectroradiometry)



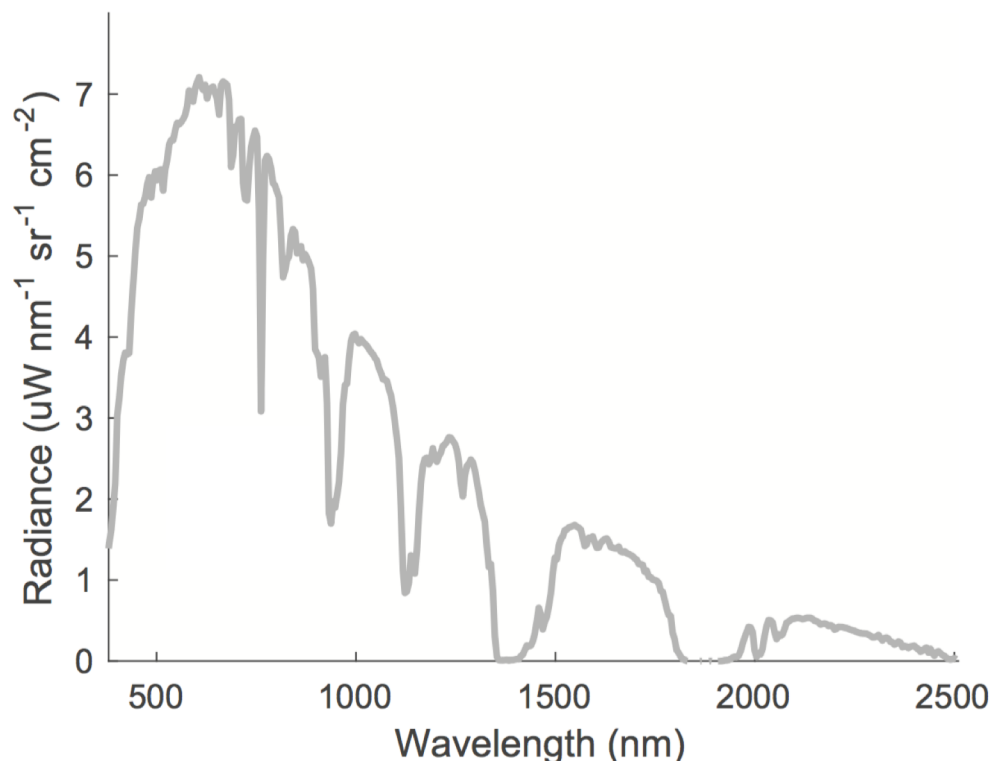
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In-flight refinement of spectral calibration via atmospheric features

Feature positions provide accurate wavelength calibration

Depths and shapes provide refined information on spectral response function



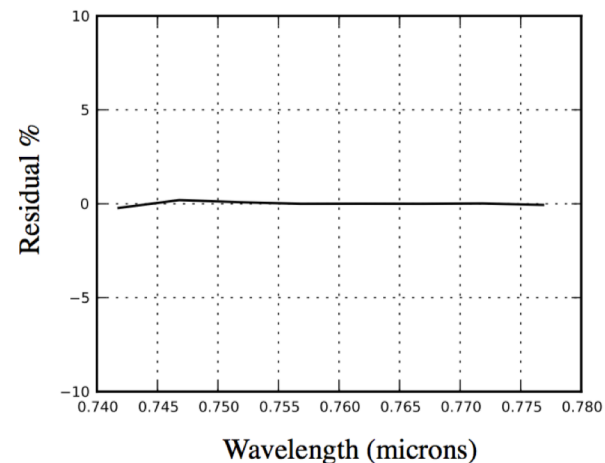
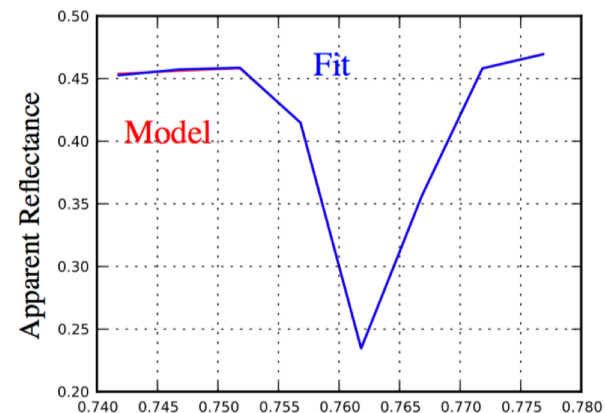
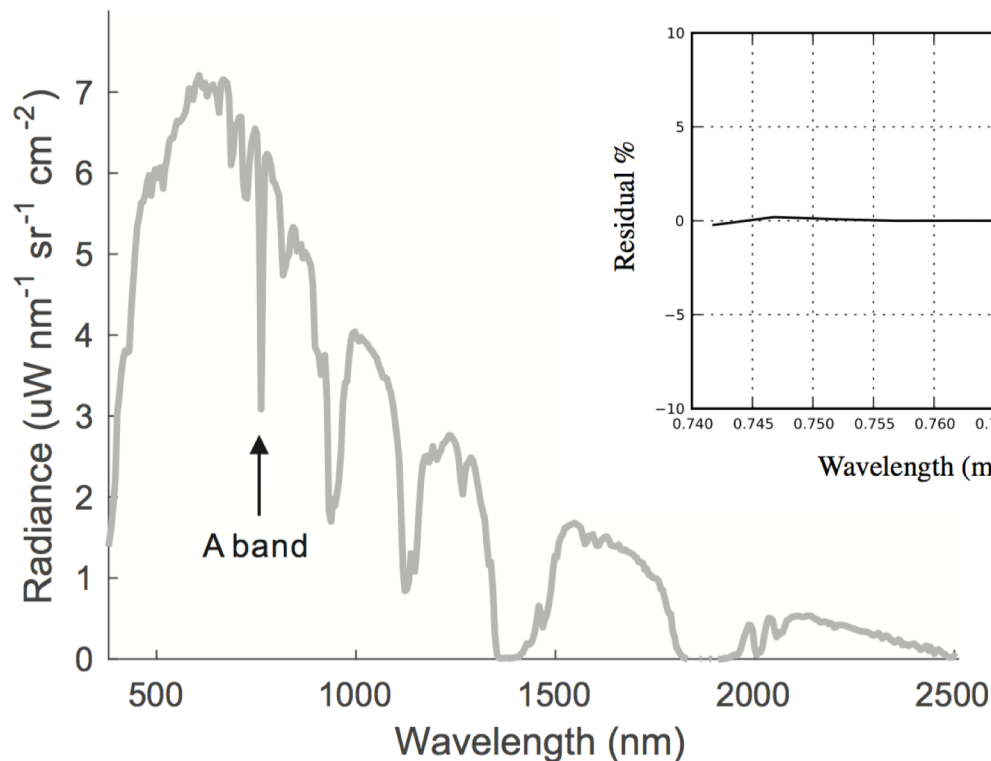
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In-flight refinement of spectral calibration via atmospheric features

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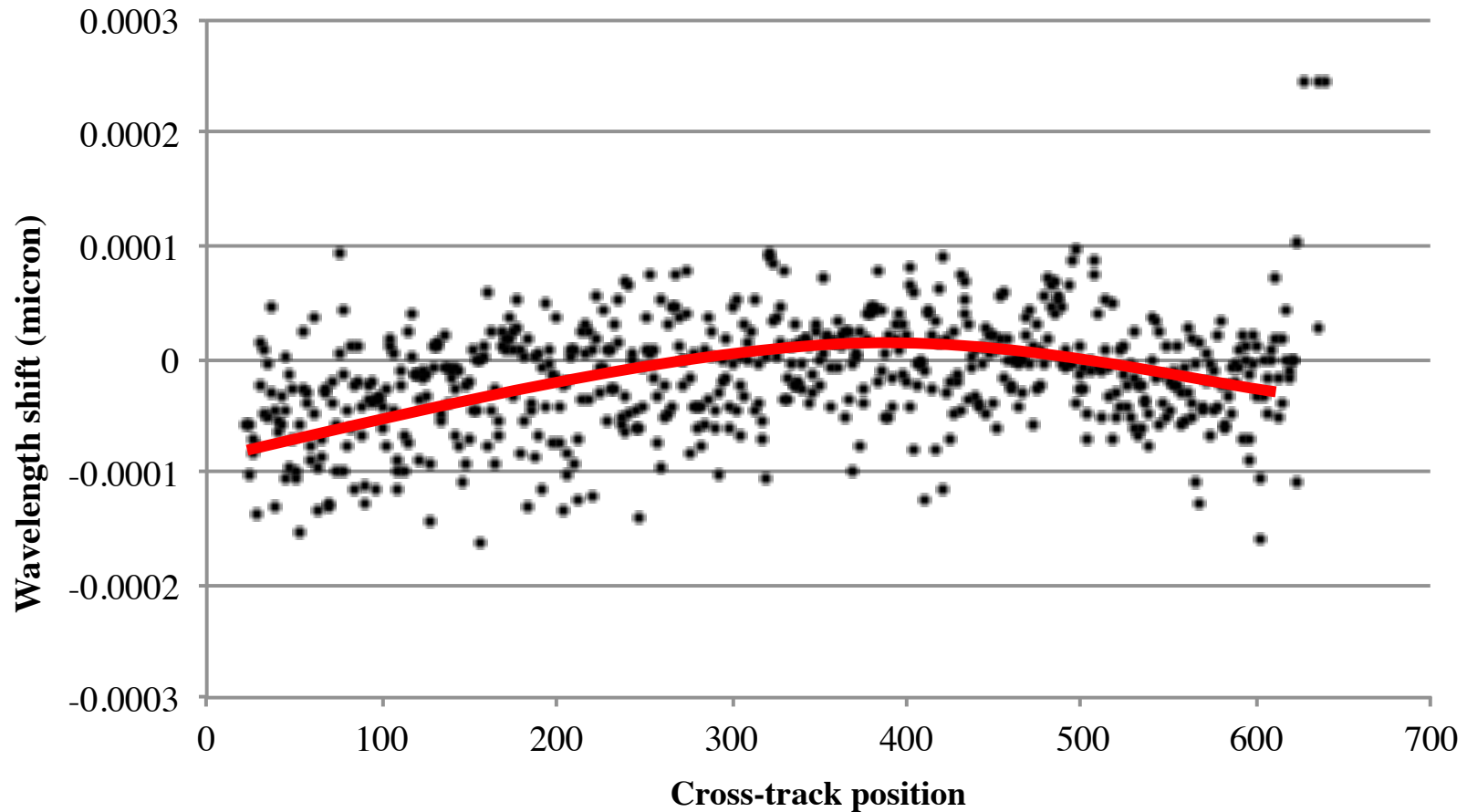


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Empirical channel positions

[Thompson et al., *Atmospheric Measurement Techniques* 2015]



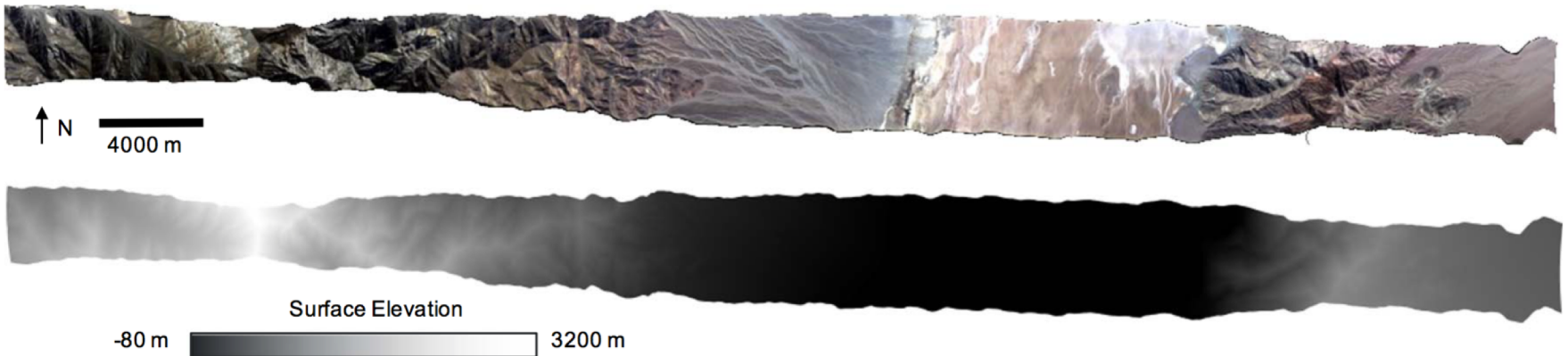
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Empirical spectral response

[Thompson et al., *Remote Sensing of Environment* 2018]

Death Valley Transect, 2014 (visible RGB)

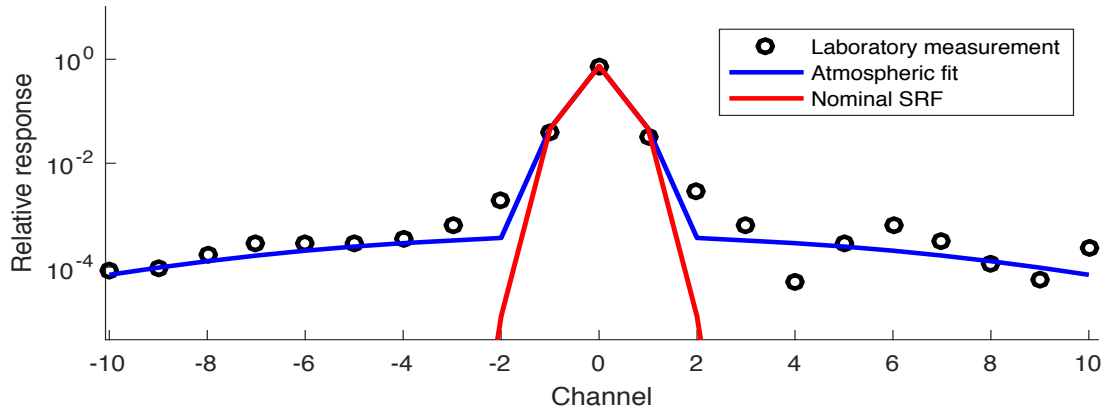


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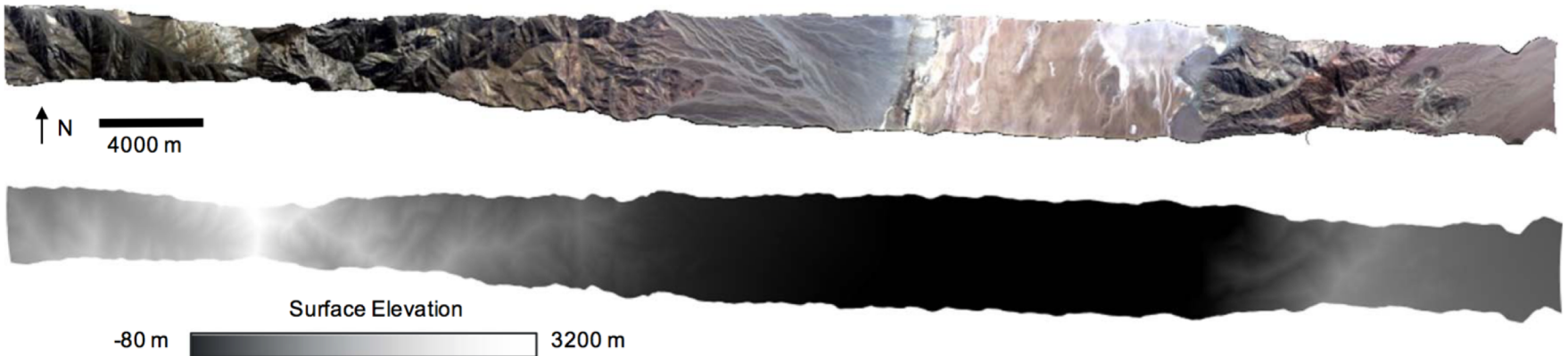
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Empirical spectral response

[Thompson et al., *Remote Sensing of Environment* 2018]



Death Valley Transect, 2014 (visible RGB)

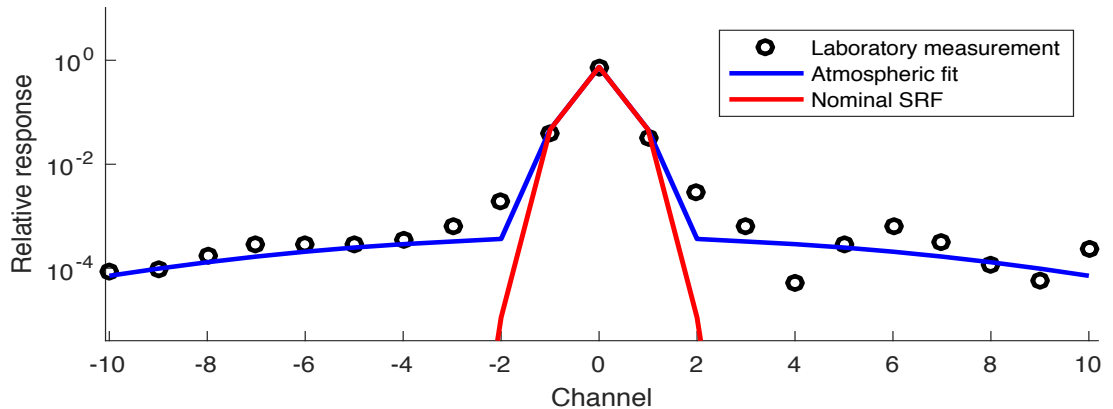


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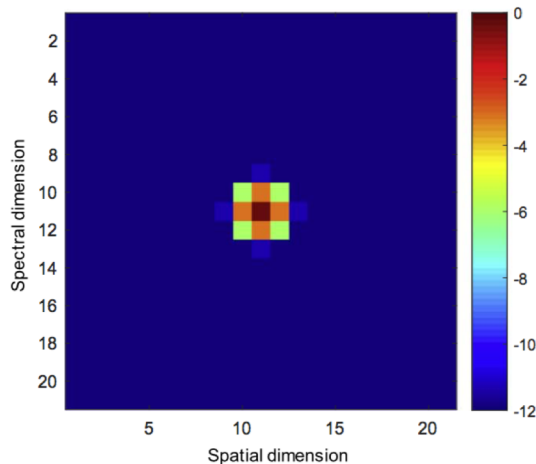
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Empirical spectral response

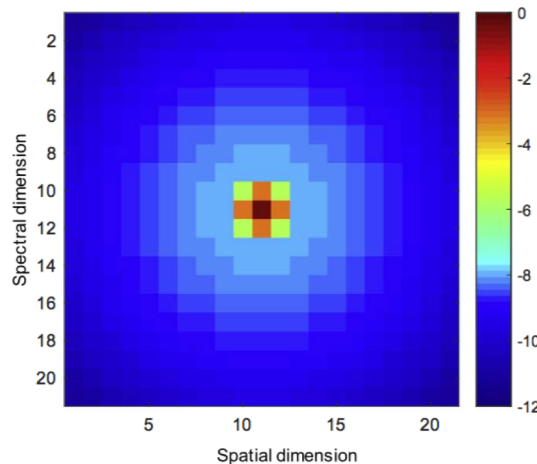
[Thompson et al., *Remote Sensing of Environment* 2018]



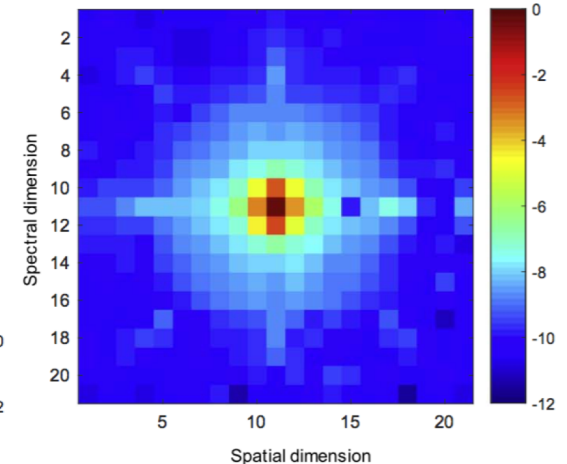
Nominal response



Atmospheric fit



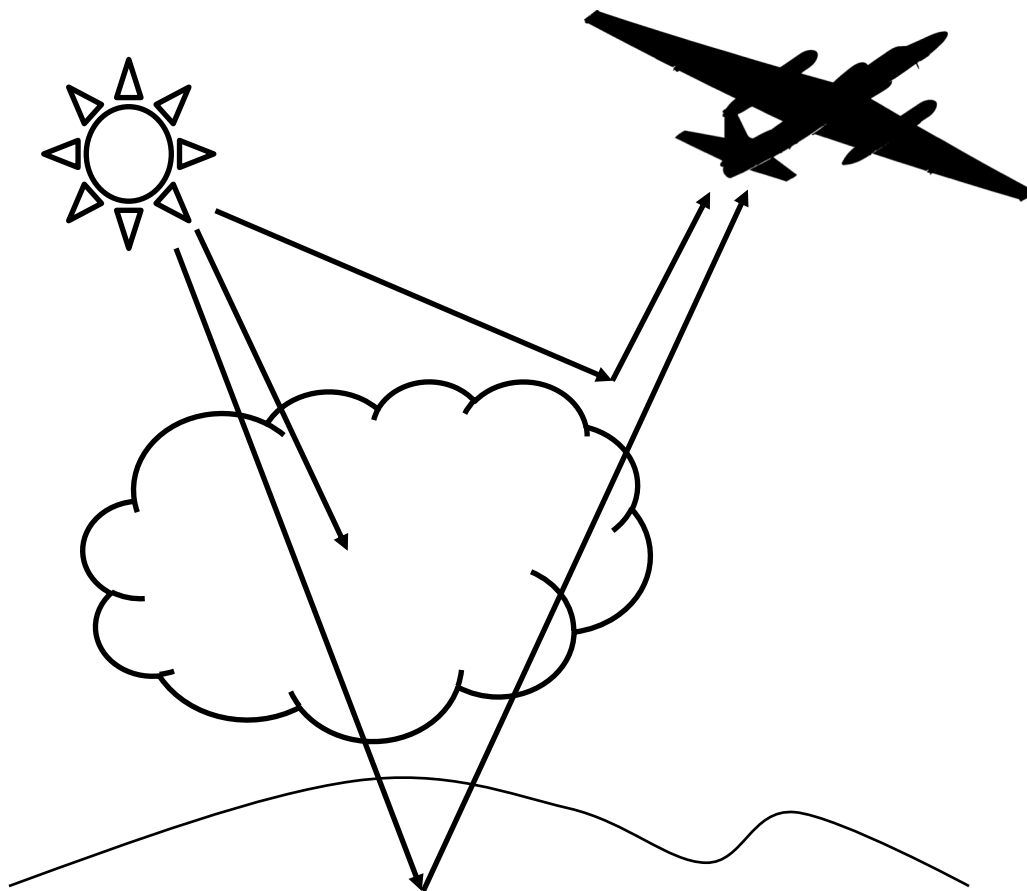
Laboratory measurement



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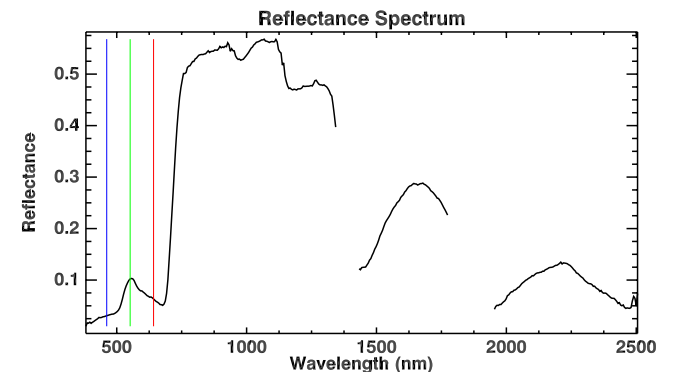
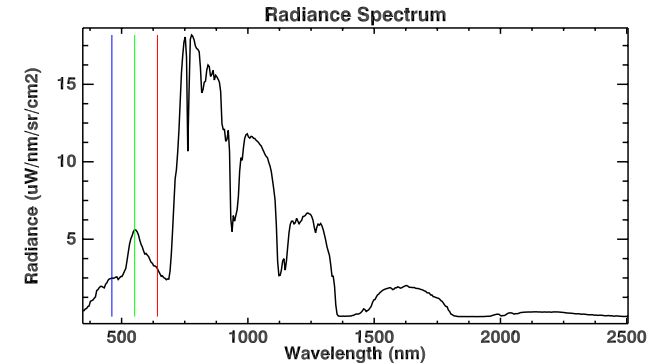
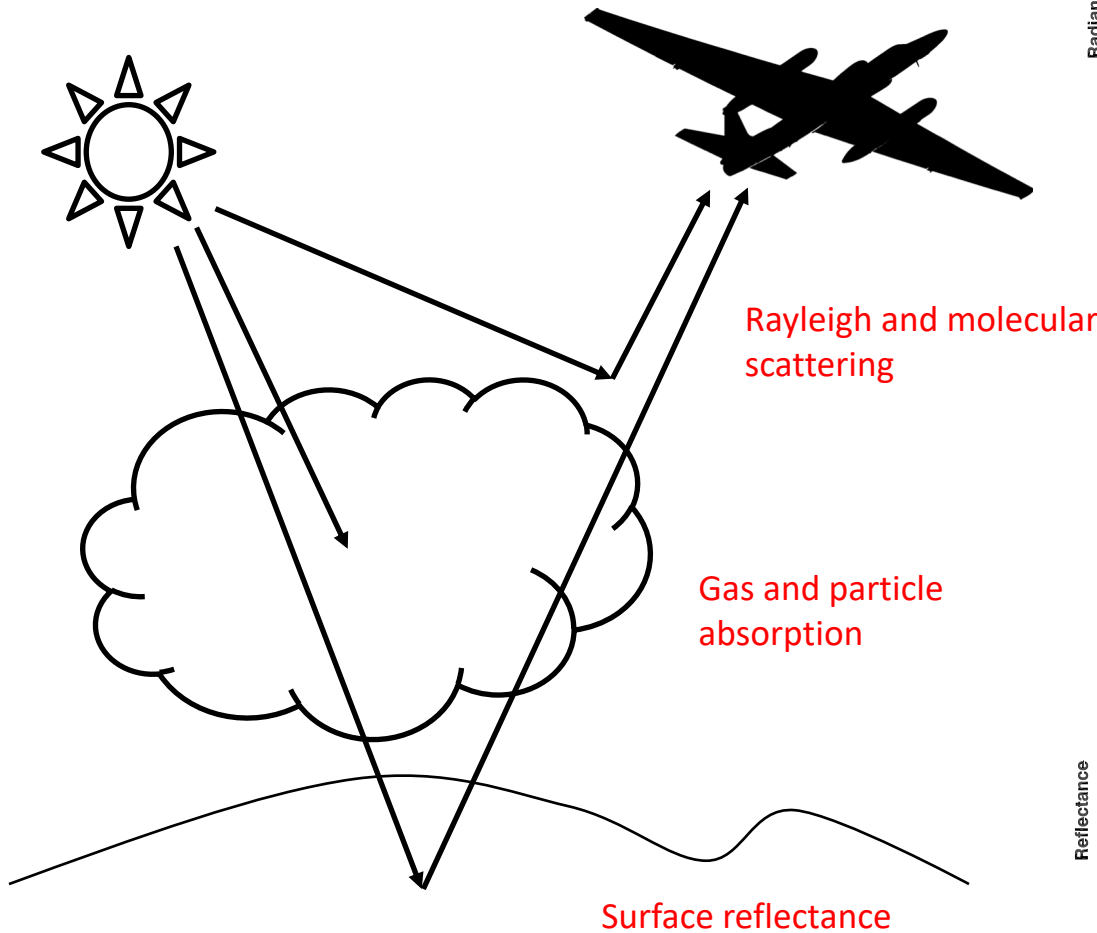
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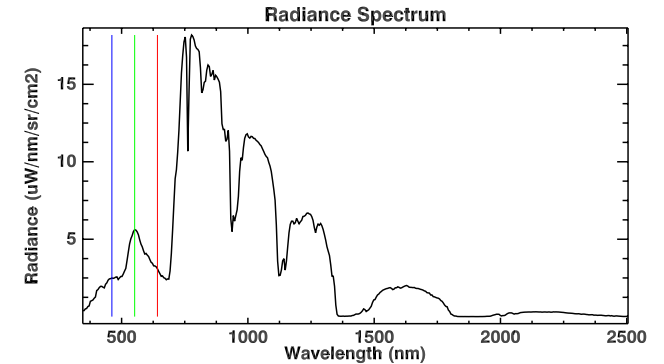
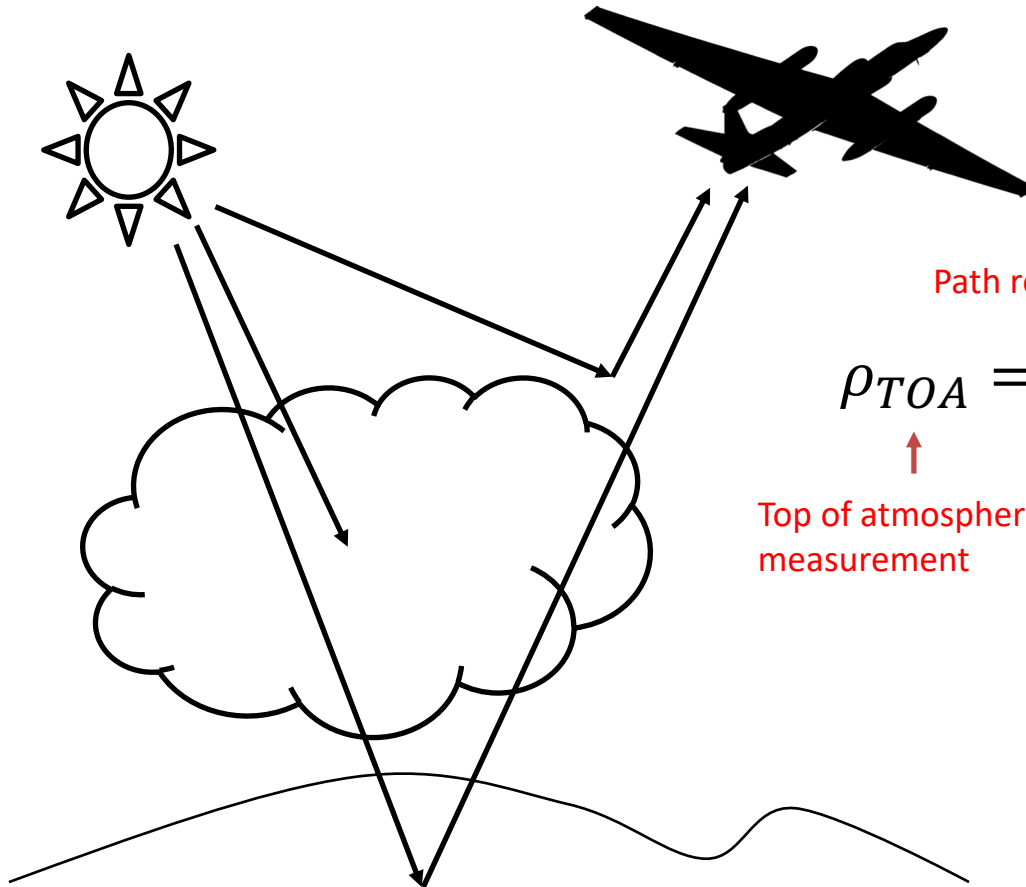
Atmospheric Correction



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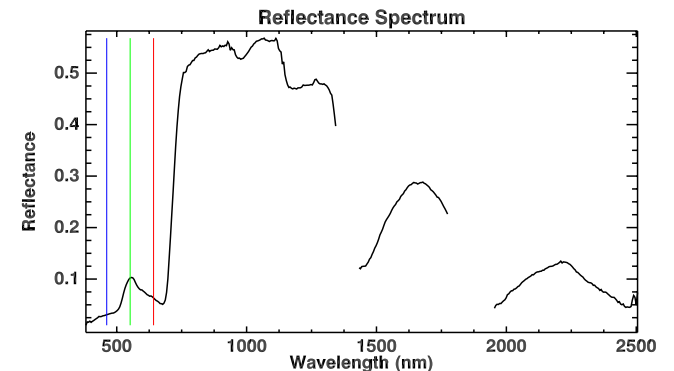
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Atmospheric Correction



$$\rho_{TOA} = \rho_{atm} + \frac{T \rho_s}{1 - S \rho_s}$$

Path reflectance \downarrow
 Top of atmosphere measurement \uparrow
 Transmission \downarrow
 Surface reflectance \leftarrow
 Spherical albedo \uparrow

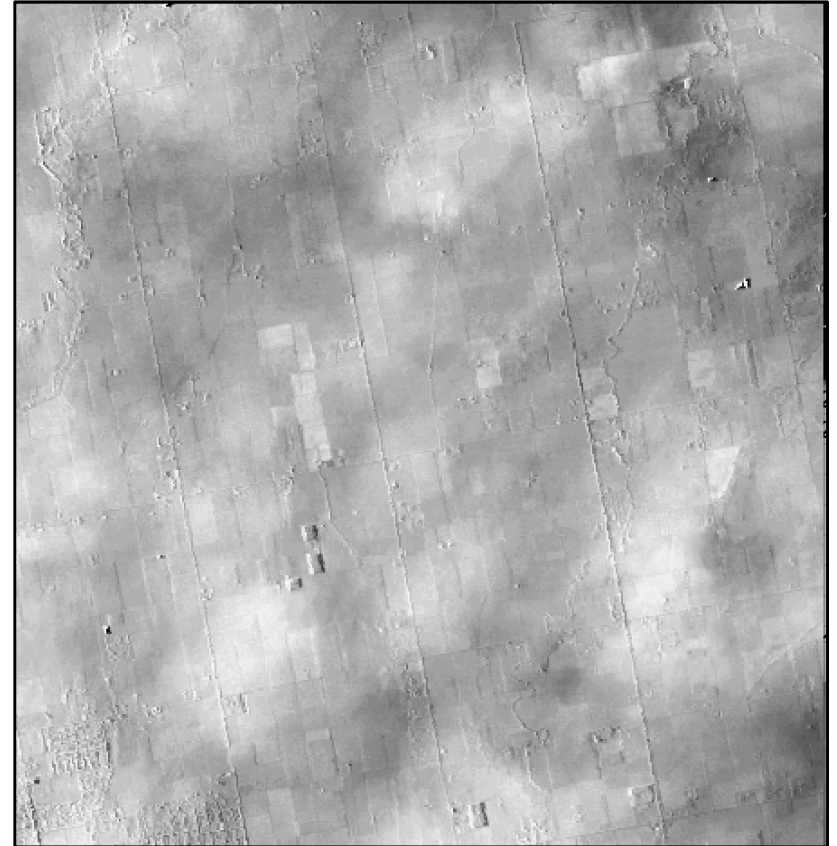


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H₂O Vapor maps

[Thompson et al., *Surveys in Geophysics* 2018]



Central Valley Agriculture (HyspIRI Santa Barbara Box)



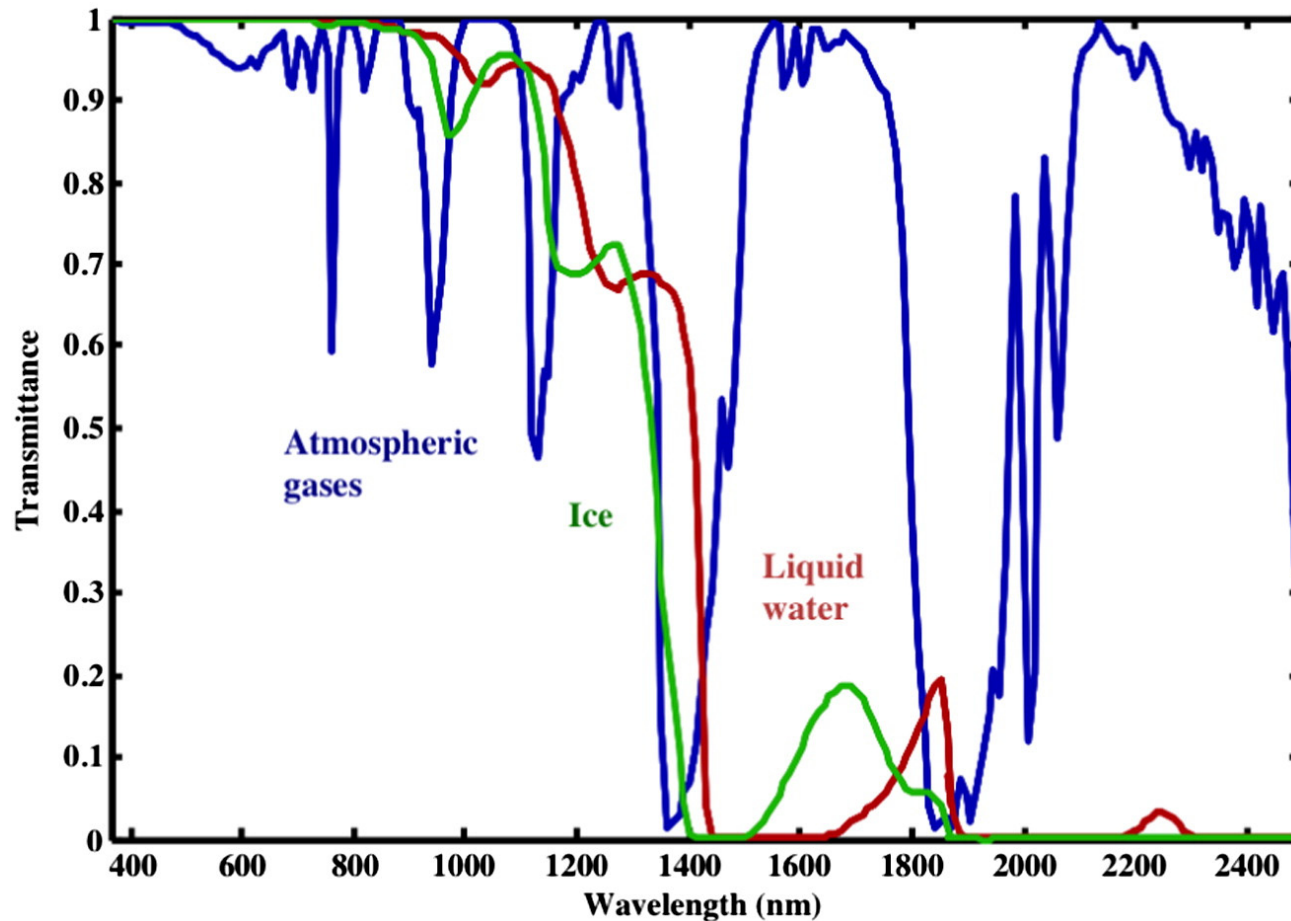
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Improving accuracy with simultaneous fitting of water vapor, ice, and liquid

[Thompson et al., *Remote Sensing of Environment* 2015]

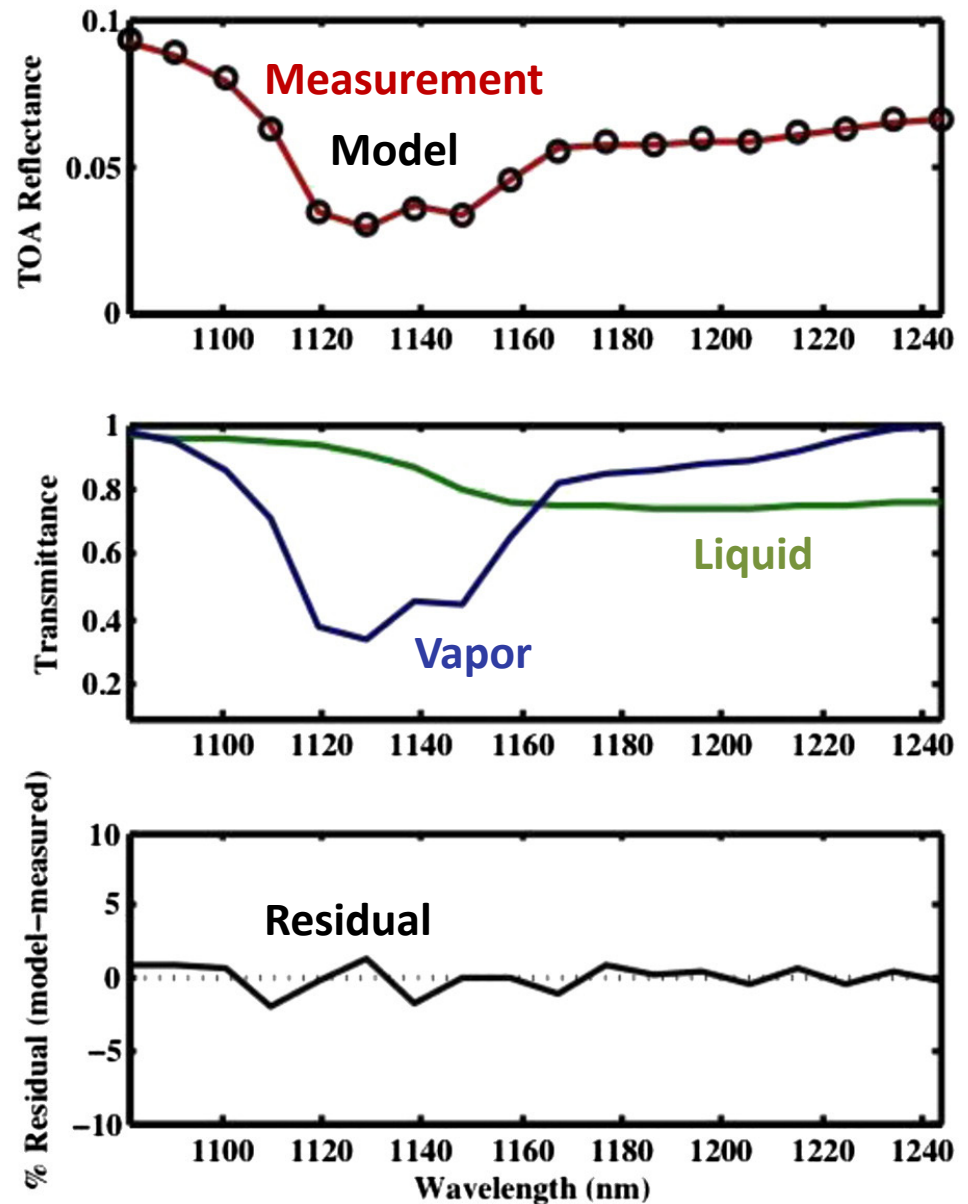
[Green et al., *Water Resources Research* 2006]



Improving accuracy with simultaneous fitting of water vapor, ice, and liquid

[Thompson et al., *Remote Sensing of Environment* 2015]

[Green et al., *Water Resources Research* 2006]



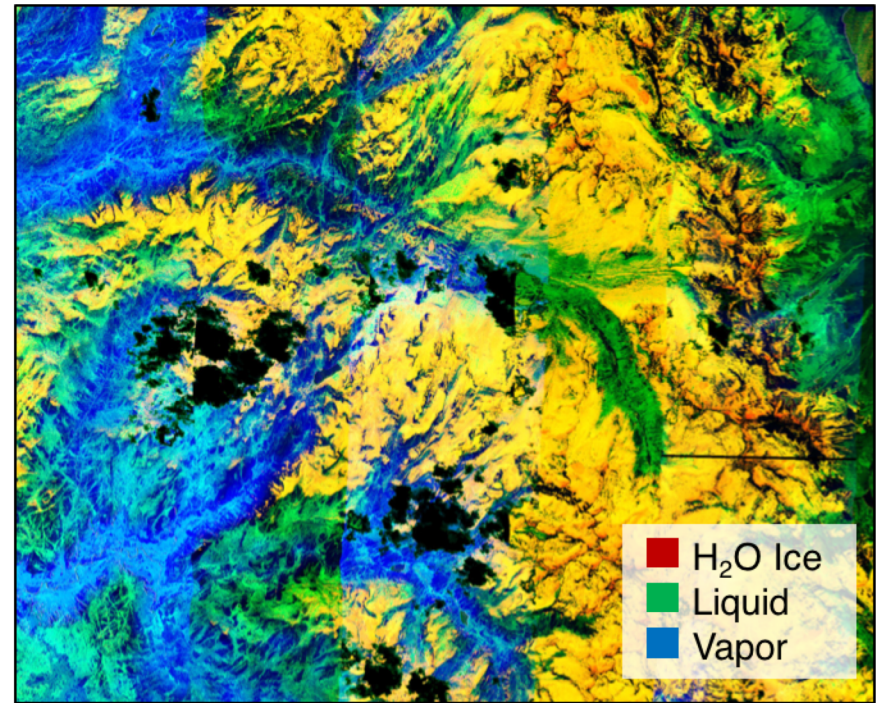
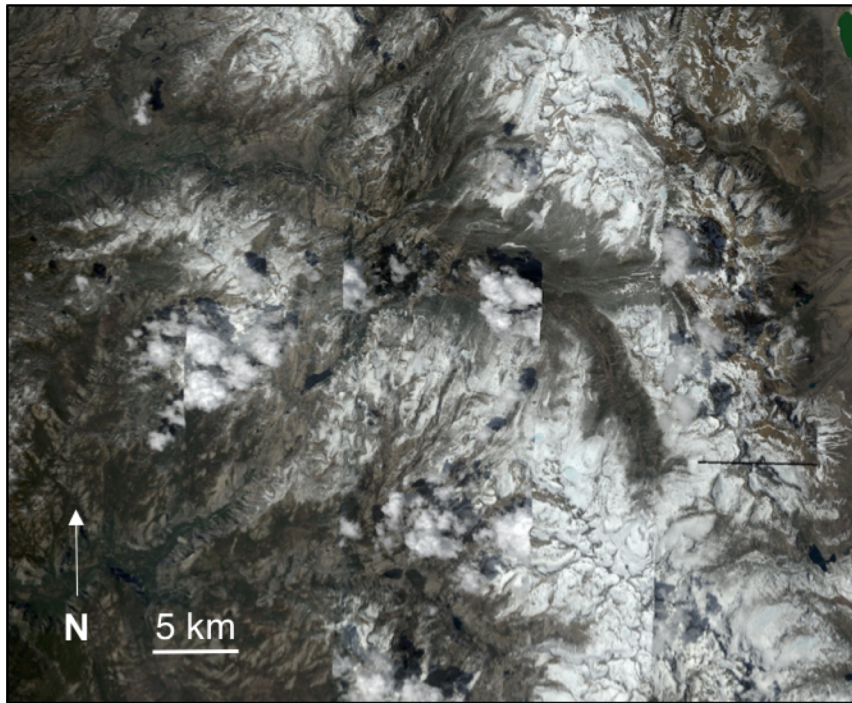
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Three phases of water

[Thompson et al., *Surveys in Geophysics* 2018]

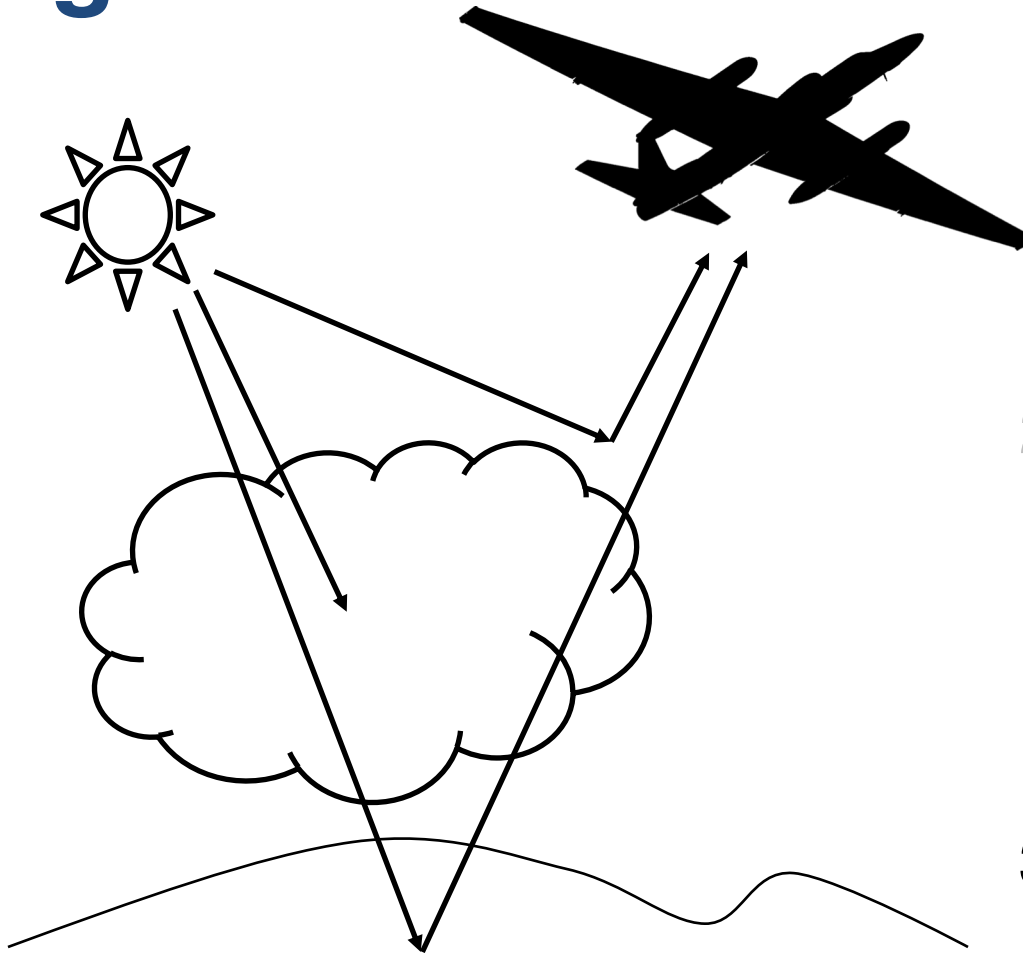
Yosemite National Park (HyspIRI Sierra Box)



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Agenda



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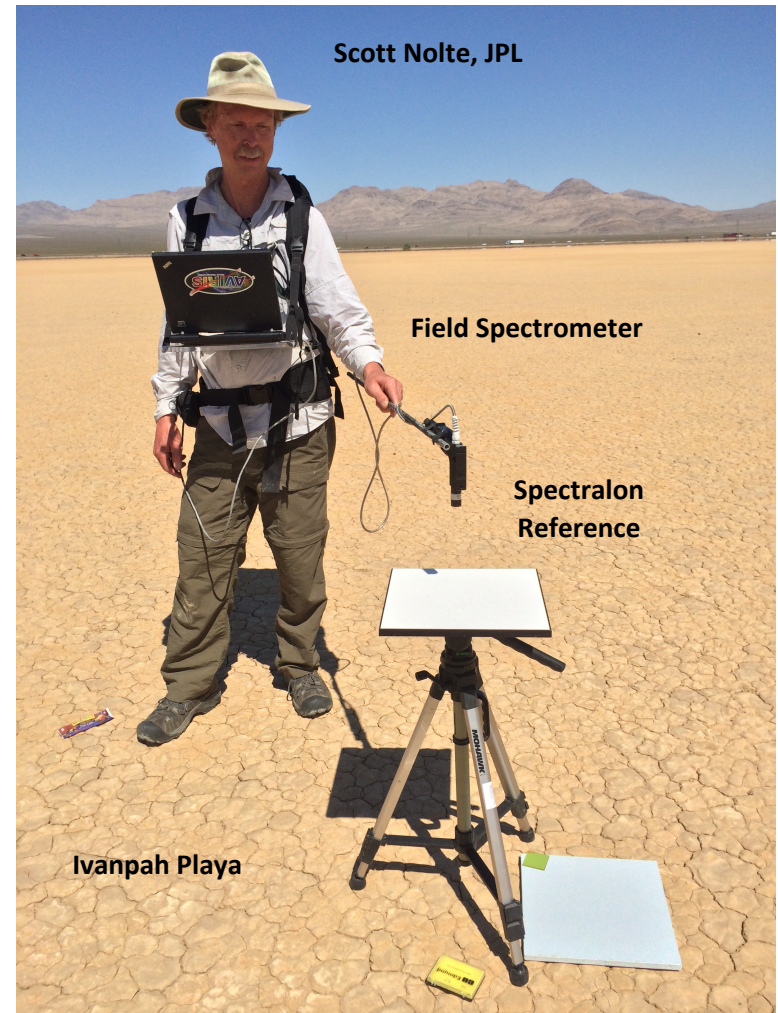
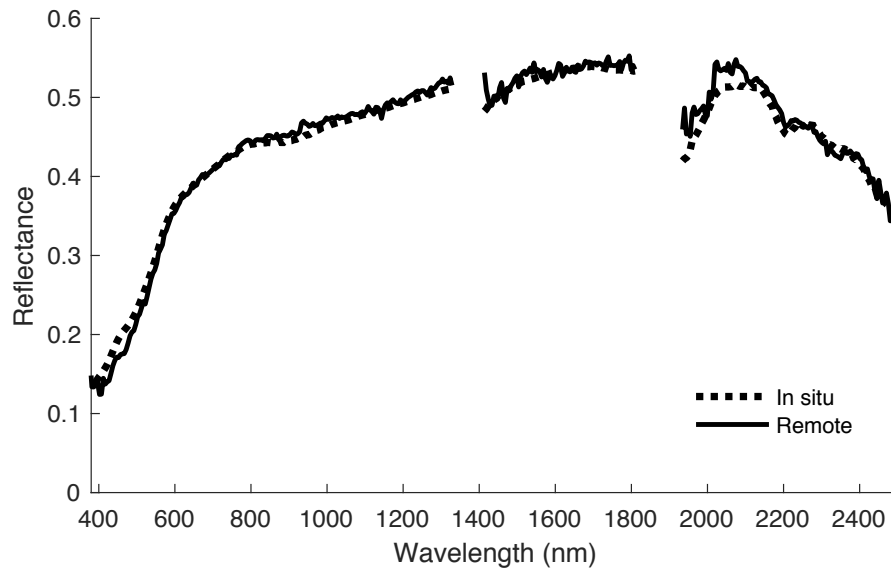


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Ivanpah field validation

[Thompson et al., *Surveys in Geophysics* 2018]

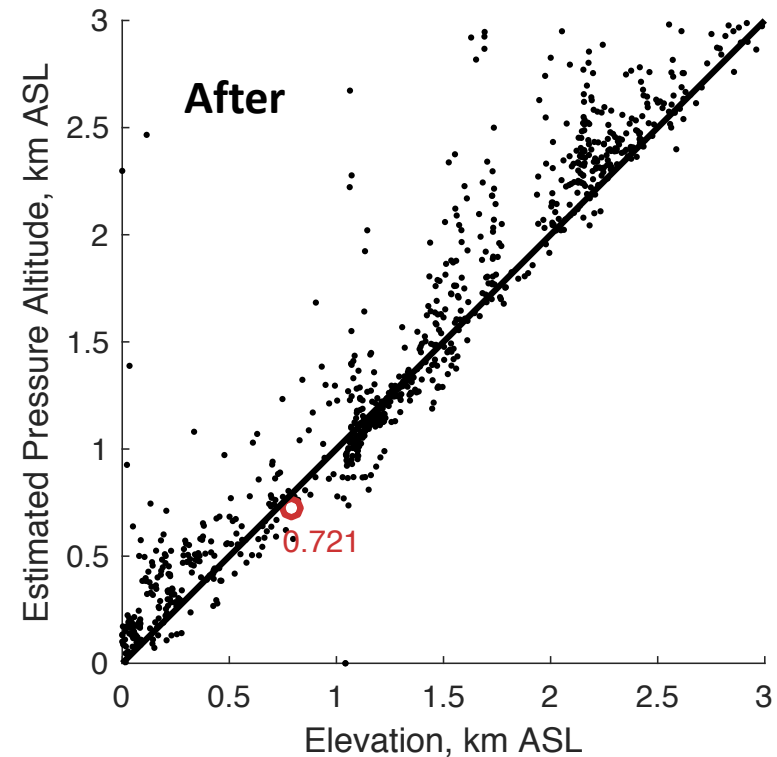
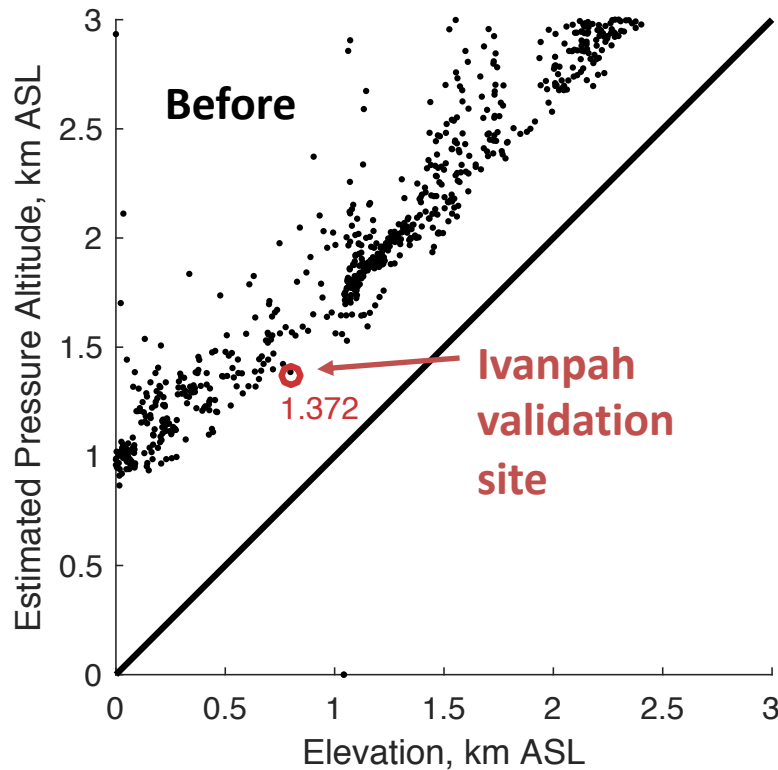


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Spectral corrections improve atmosphere retrievals

[Thompson et al., *Remote Sensing of Environment* 2018]



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Ongoing: *Optimal Estimation* for iterative fits of surface and atmosphere

[Thompson et al., *Remote Sensing of Environment* 2018]

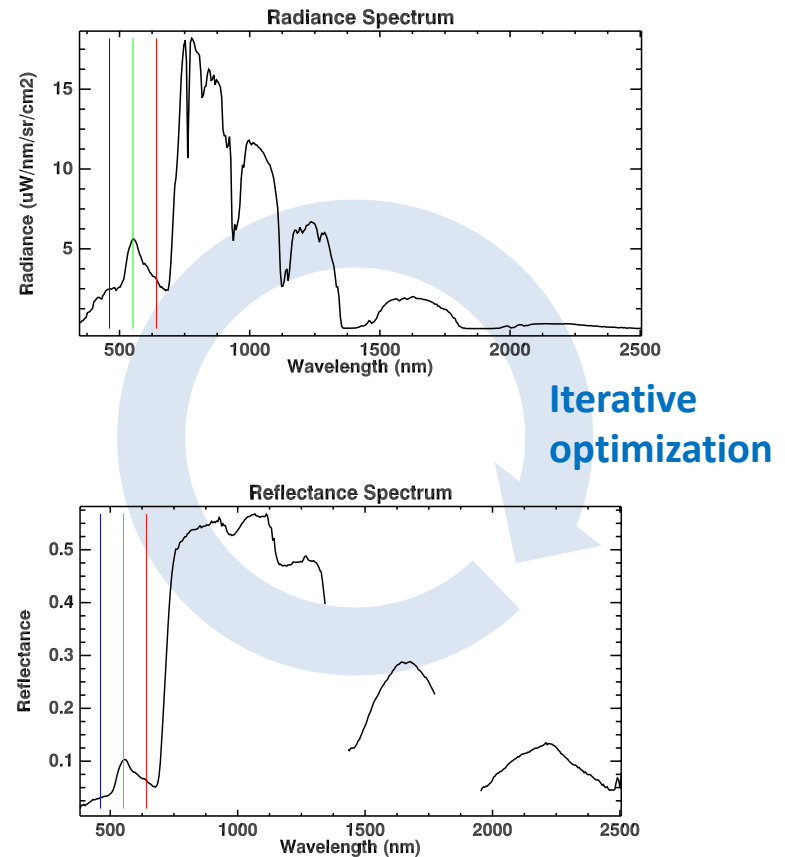
Bayesian *Maximum a Posteriori* estimate using a combined model of surface, atmosphere, instrument

Improves atmospheric correction accuracy

Rigorous uncertainty accounting

Optimal weighting of information from instrument vs. domain knowledge

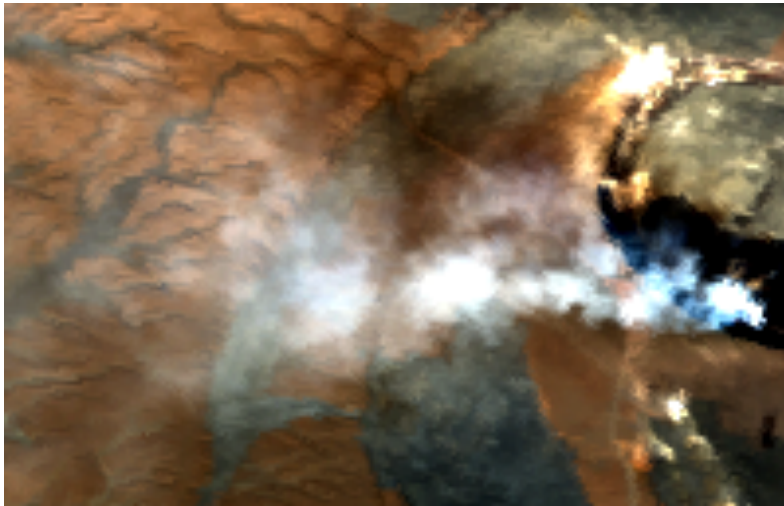
<https://github.com/isofit/isofit>



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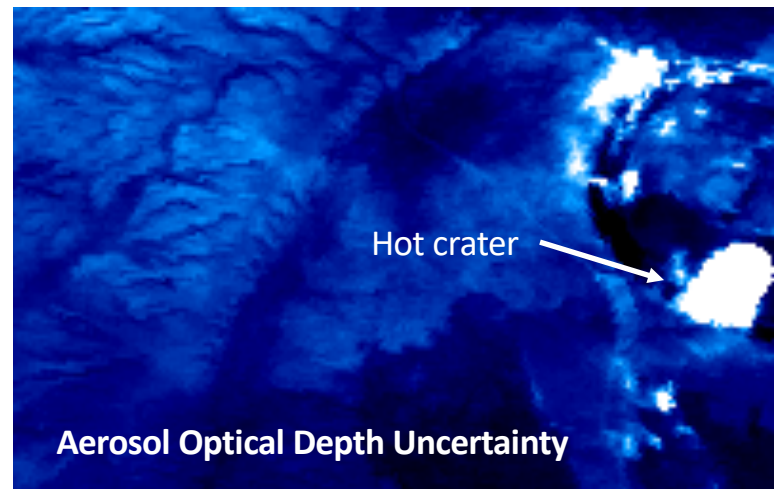
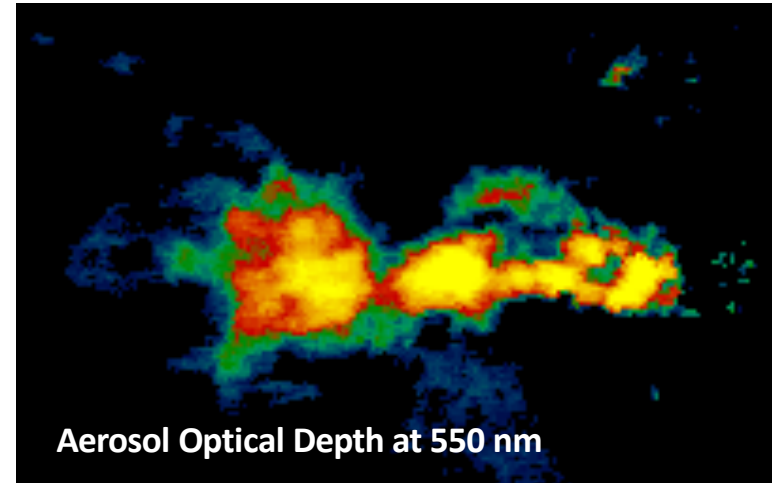
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Example: volcano observations



AVIRIS-C f170127t01p00r16
(subset, visible bands)

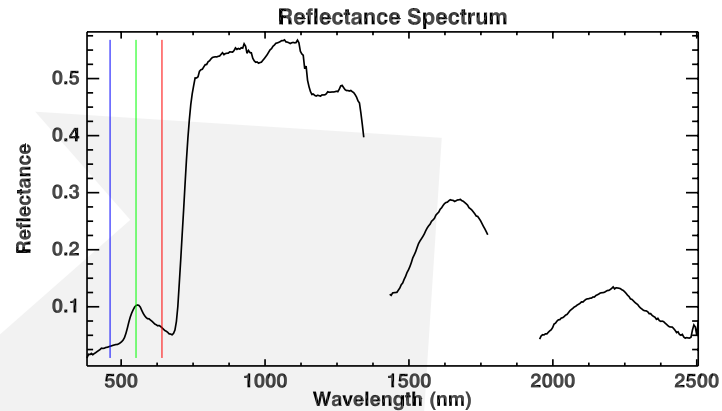
Combined estimate of H₂O vapor, AOT,
surface reflectance and temperature



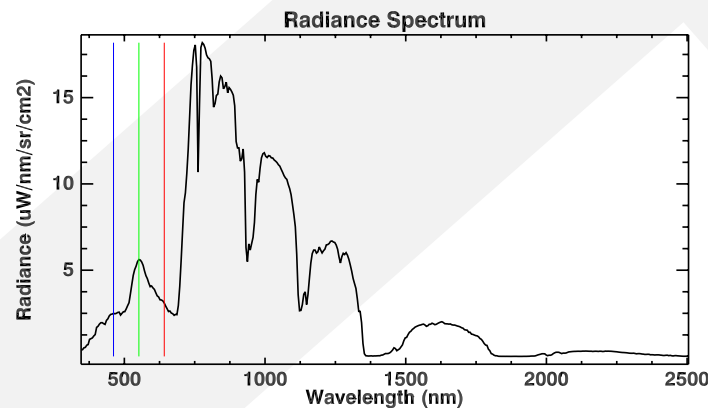
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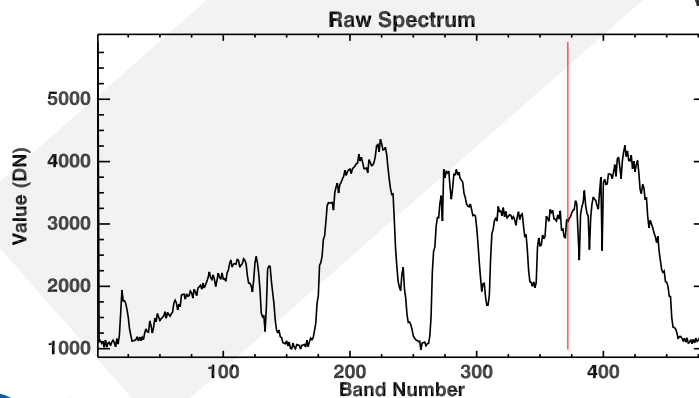
Summary



**Lambertian
Reflectance
(HDRF)**



**Radiance at
sensor
mW/nm/cm²/sr**



**Raw Digital
Numbers**

**[Gao et al., 1993;
Green et al., 1998,
Thompson et al., 2015]**



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Thanks!

NASA Earth Science Division and the HypsIRI preparatory campaign

The AVIRIS-NG Team, including Sarah Lundeen, Brian D. Bue, Winston Olson-Duvall, John Chapman, and others

NASA Program NNH16ZDA001N-AVRSN, “Utilization of Airborne Visible/Infrared Imaging Spectrometer – Next Generation Data from an Airborne Campaign in India.” Program manager Woody Turner



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BACKUP

Stray SRF Measurement model

Adapted from [Zhong et al., 2006]

$$\text{Measured Radiance} = \text{Stray Radiance} + \text{Nominal Radiance} + \text{Measurement Noise}$$



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Stray SRF Measurement model

Adapted from [Zhong et al., 2006]

$$\begin{array}{ccccccc} \text{Measured} & & \text{Stray} & & \text{Nominal} & & \text{Measurement} \\ \text{Radiance} & = & \text{Radiance} & + & \text{Radiance} & + & \text{Noise} \\ & & \downarrow & & \downarrow & & \downarrow \\ L_M & = & GHL_A & + & HL_A & + & \epsilon \\ & & \uparrow \quad \uparrow & & \uparrow & & \\ & & \text{Stray SRF} \quad \text{Nominal SRF} & & \text{Radiance at sensor} & & \end{array}$$



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Stray SRF Measurement model

Adapted from [Zhong et al., 2006]

$$\begin{array}{ccccccc} \text{Measured} & & & & & & \\ \text{Radiance} & = & \text{Stray} & & \text{Nominal} & & \text{Measurement} \\ & & \text{Radiance} & + & \text{Radiance} & + & \text{Noise} \\ & & \downarrow & & \downarrow & & \downarrow \\ \mathbf{L}_M & = & \mathbf{GHL}_A & + & \mathbf{HL}_A & + & \epsilon \\ & & \uparrow & \uparrow & \uparrow & & \\ & & \text{Stray SRF} & \text{Nominal SRF} & \text{Radiance at sensor} & & \end{array}$$

$$\mathbf{L}_M = [\mathbf{G} + \mathbf{I}] \mathbf{L}_N + \epsilon$$

$$\mathbf{L}_M = \mathbf{A} \mathbf{L}_N + \epsilon$$



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A Linear SRF Correction Matrix

Calculate a Moore-Penrose Pseudoinverse:

$$\mathbf{A}^+ = (\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T$$

This estimates the nominal SRF:

$$\hat{\mathbf{L}}_N = \mathbf{A}^+ \mathbf{L}_M$$

Corrected Radiance Correction matrix Distorted Measurement

A similar correction fixes cross-track stray light

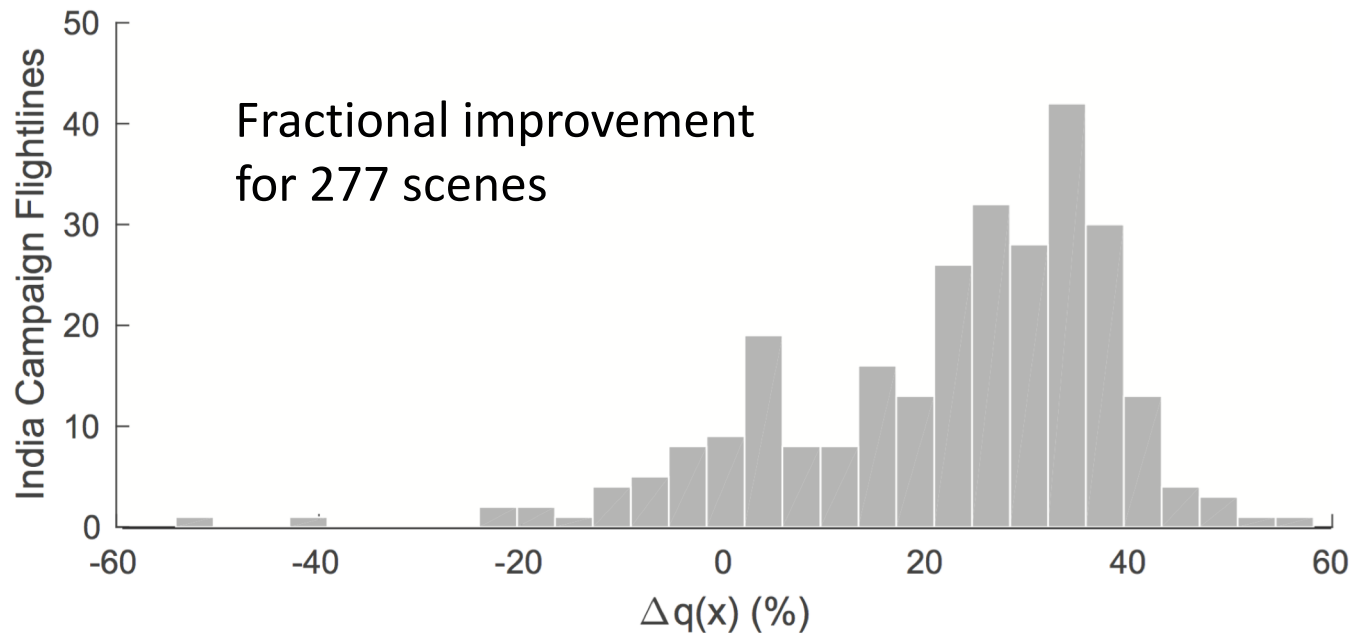


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India Validation Results

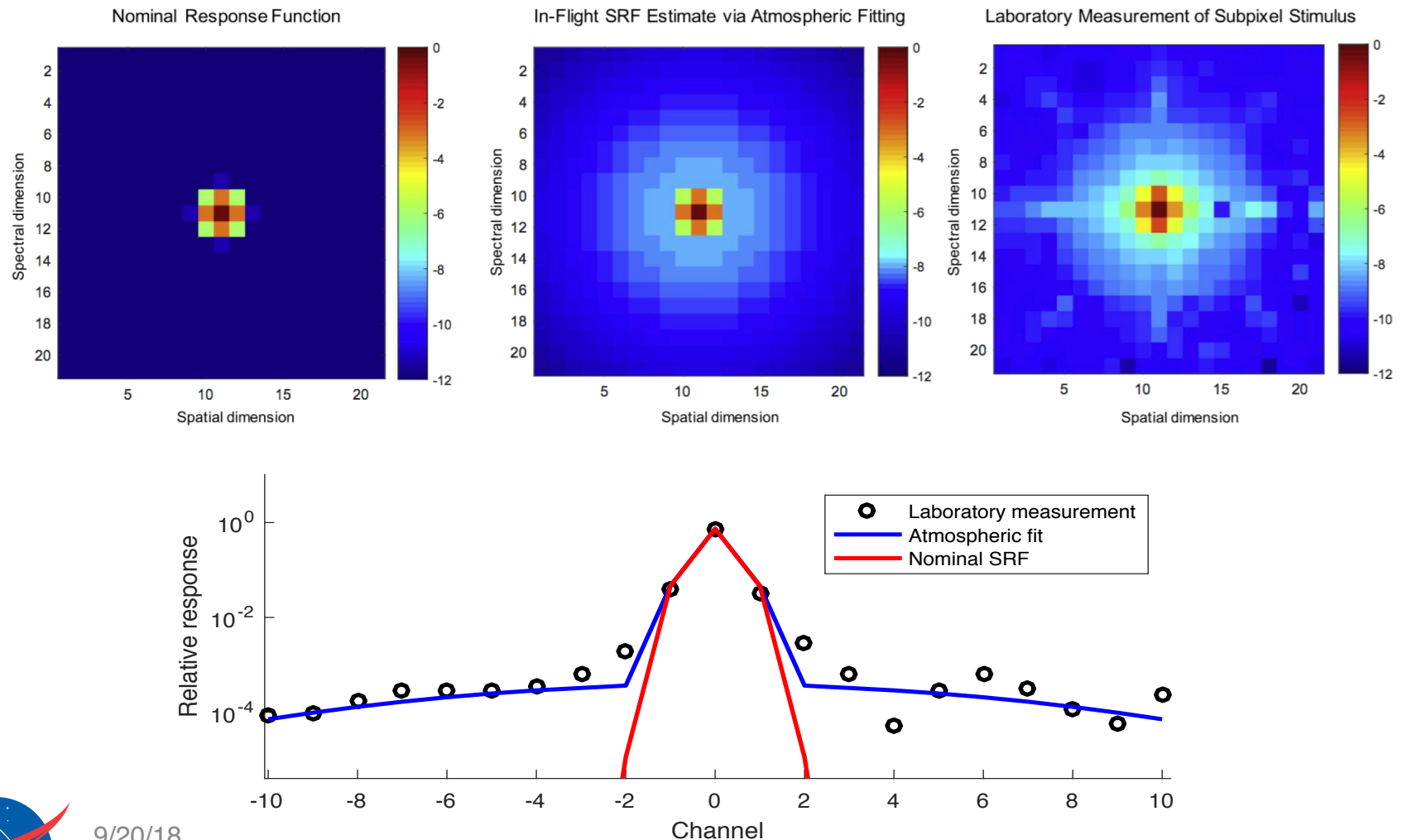
- 26 of 37 flight days show significant improvements ($p < 0.001$)
- Typical improvement is 20-35%
- No flight day shows a statistically significant accuracy reduction



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Agreement with laboratory data

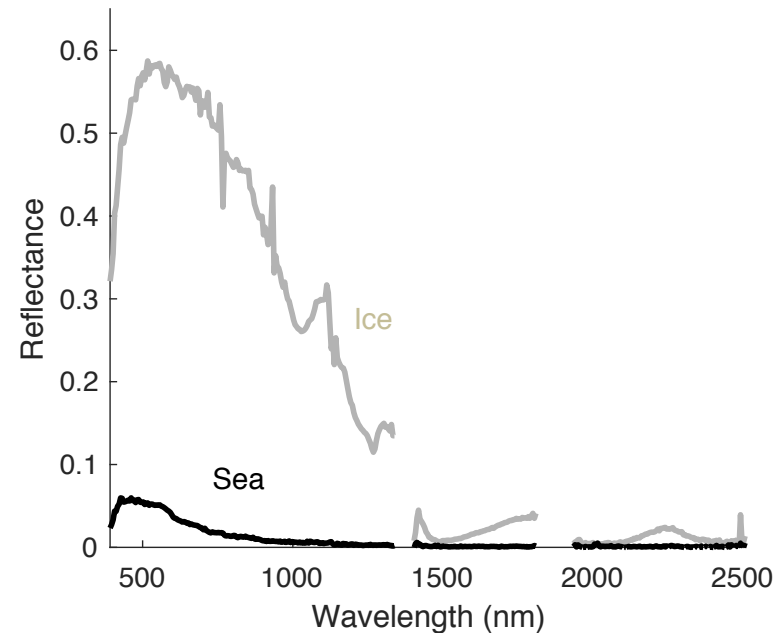


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Spatial dimension

- Exploit Near-Infrared (NIR) ocean reflectance
- Use a haze-free day to constrain path radiance and adjacency effects
- Use a wind-free day with nadir observations to limit glint
- Dark water should be highly absorbant in NIR
- Dataset: 2015 Greenland ice flow



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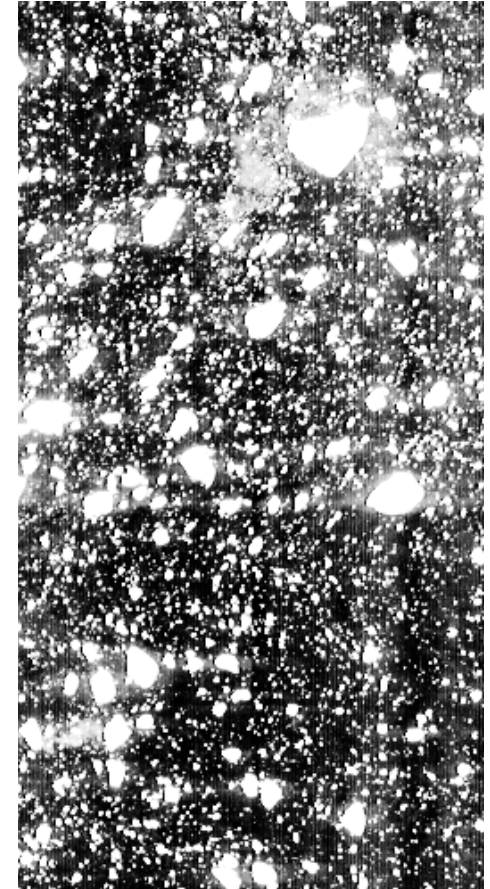
“Halo” reduction



Original RGB



612 nm, equalization stretch
(0-3 $\mu\text{W nm}^{-1} \text{sr}^{-1} \text{cm}^{-2}$)



612 nm, after CRF correction



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Retrieve Stray SRF from a “Calibration Scene”

Death Valley Transect, 2014 (visible RGB)



Predict A band radiances using a Digital Elevation Model



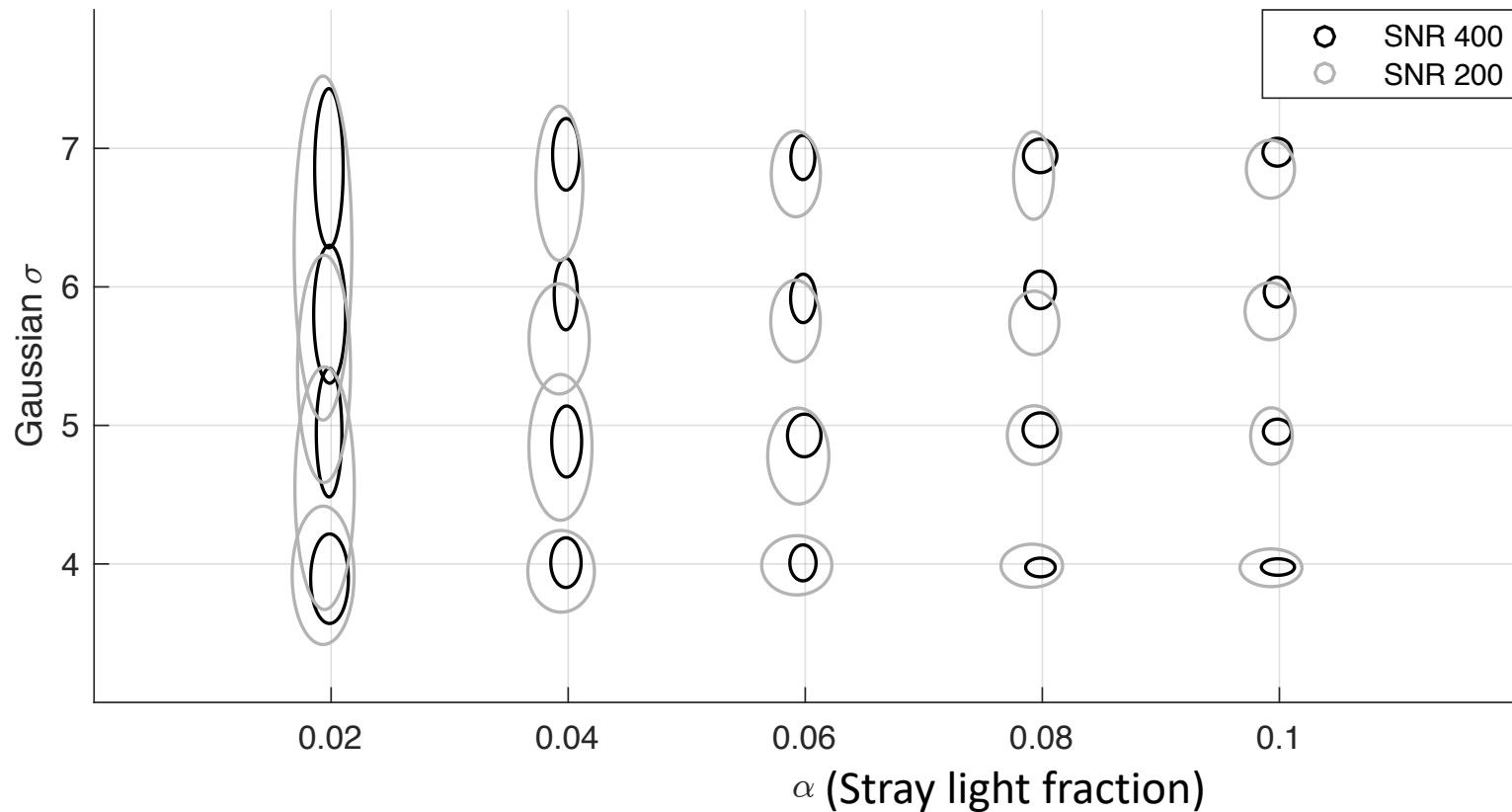
Nonlinear least squares optimization finds SSRF parameters



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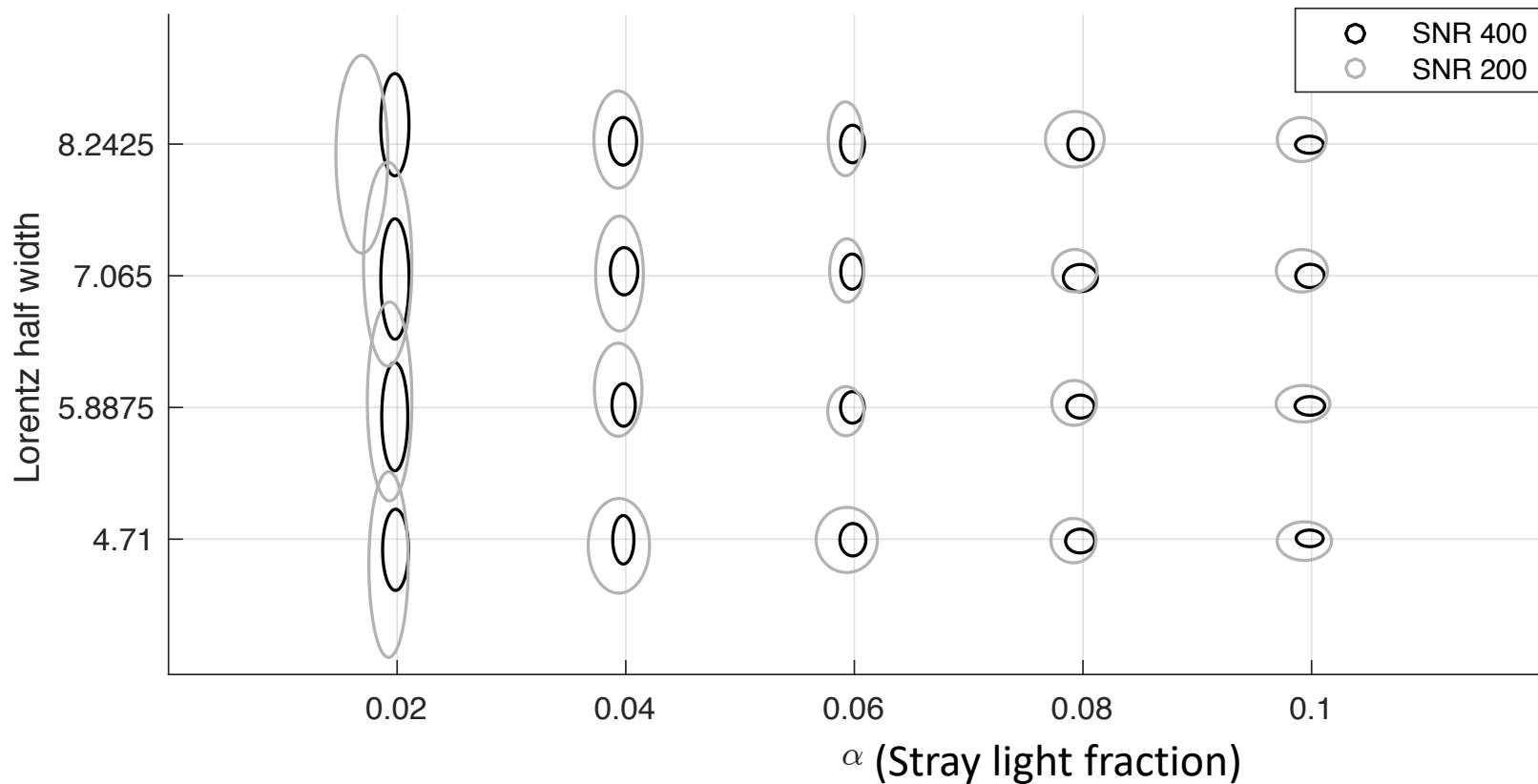
Estimation accuracy for Gaussian SSRF (simulated)



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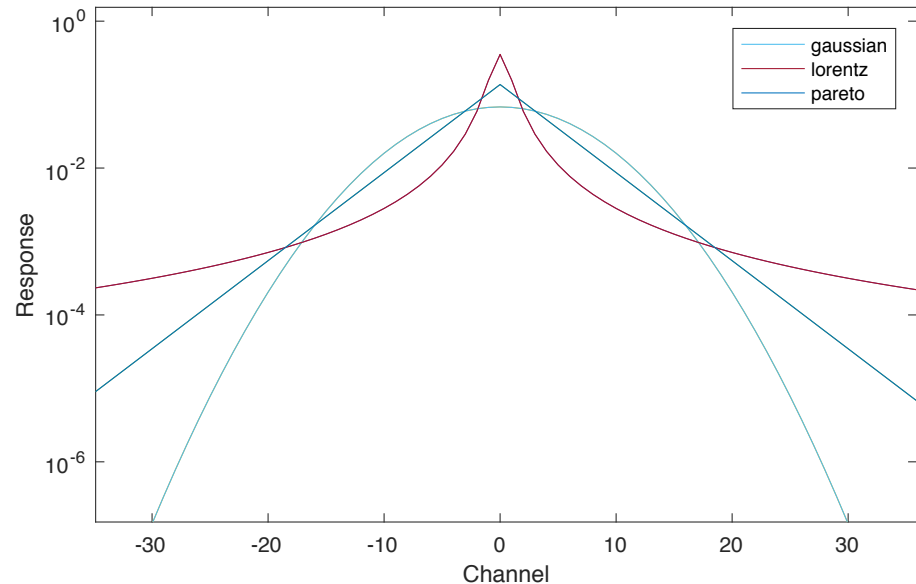
Estimation accuracy for Lorentz SSRF (simulated)



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Fit error for candidate SSRF shapes



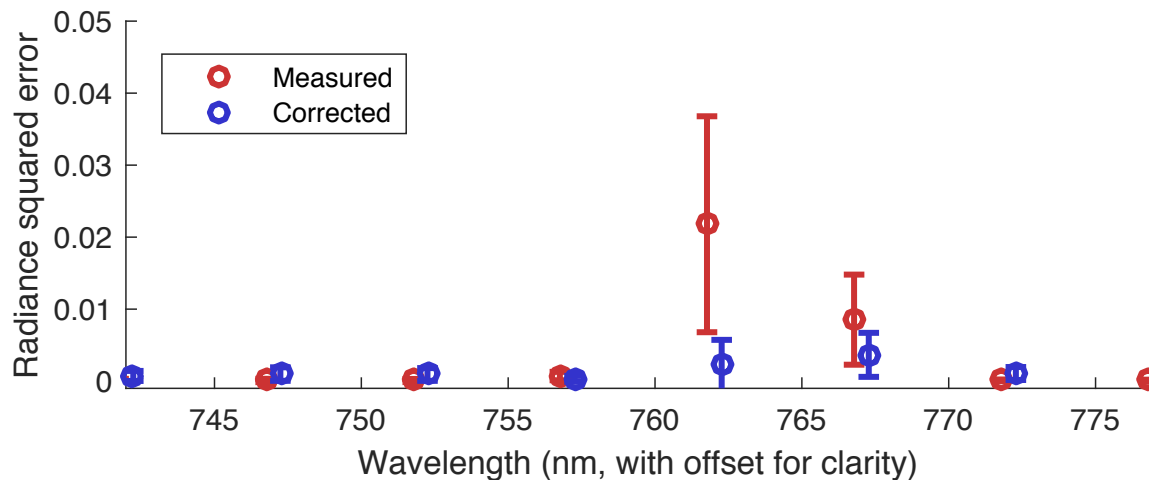
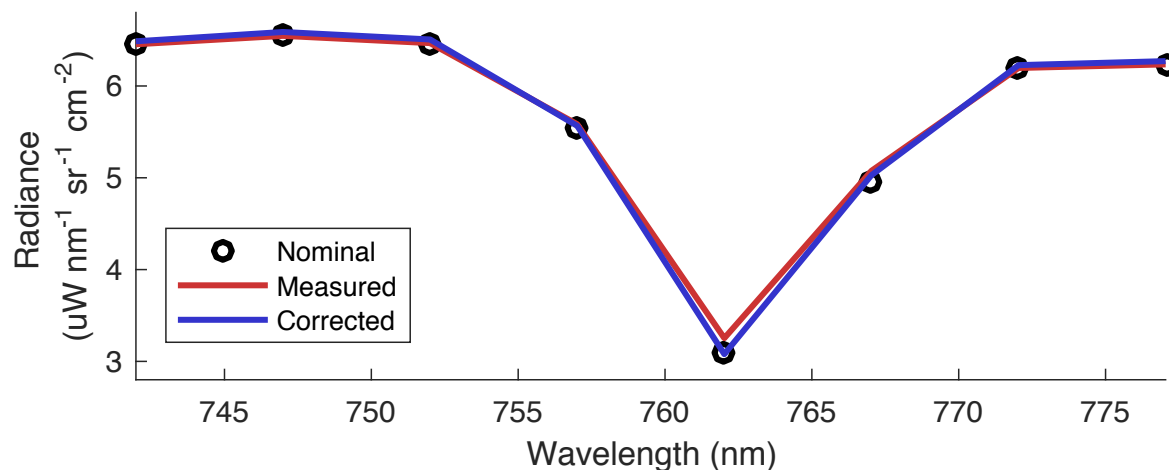
Line shape	Error	α	SSRF parameters
Original	0.04482	n/a	n/a
Pareto	0.004482	0.0805	x: 0.154, y: 0.0515
Lorentz	0.002059	0.0664	x: 1.018, y: 3.912
Voigt	0.001413	0.0639	σ : 5.477, <i>LHW</i> : 0
Gaussian	0.001413	0.0639	σ : 5.477



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Improvement in O₂ A band fit



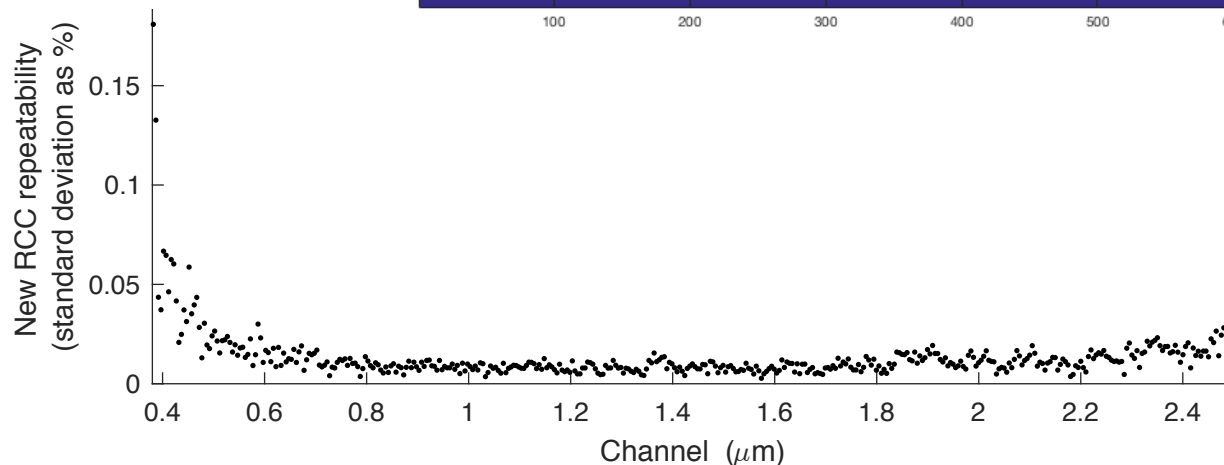
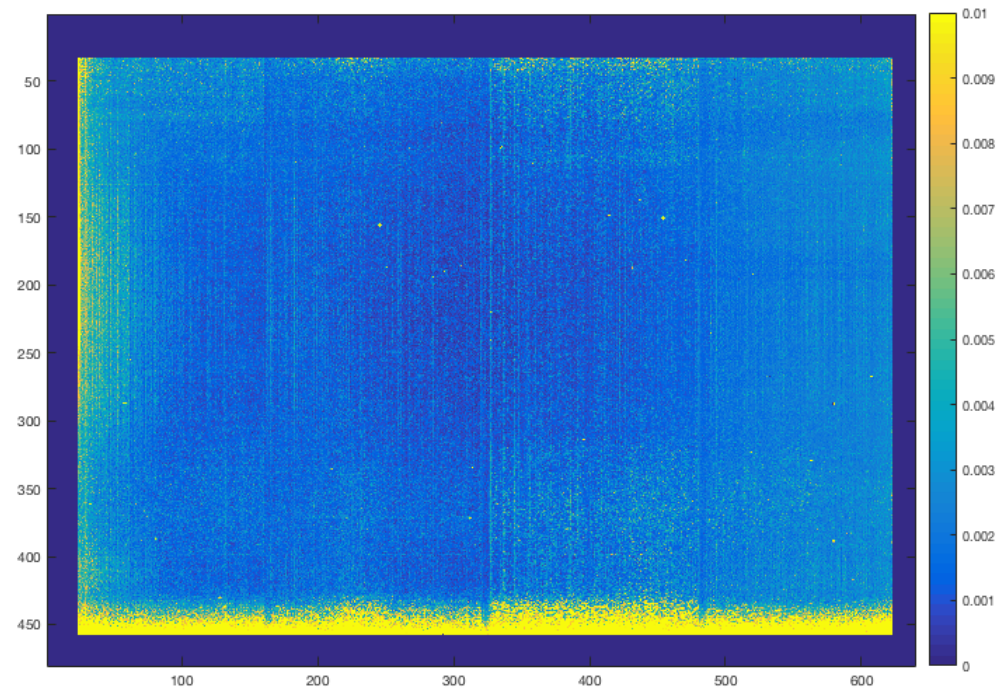
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Radiometric calibration repeatability (hangar protocol)

Calibration coefficients:
 $\sigma < 0.05\%$
across most channels

Flat field: $\sigma < 0.14\%$ across most elements



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