



Incorporating Spatial Information in Hyperspectral Unmixing

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Collaborators

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- Background
 UTEP SenSAL
 - Hyperspectral Unmixing
- Non-convexity of the data cloud
- Exploring the spatial dimension
- Proposed unmixing approach
- Experimental results
- Final Remarks



Sensor and Signal Analytics Laboratory

Expertise/Capability



Research Goals

- Develop novel systematic information extraction algorithms from remote or minimally intrusive sensing and imaging systems
 - Advanced mathematical concepts
 - Novel computational methodologies
- Provide a multi-disciplinary environment for training and research to undergraduate and graduate students in state of the art tools and technologies
 - · Partnerships with end users and industry
- Develop technology and tools to solve relevant societal problems
 - Environment, Homeland Security, Defense, Biomedical



Funders

- NSF
- NASA (with UPRM)
- UTEP Office of the Provost IDR
- UT System STARS







Linear Mixing Model





Unmixing Algorithms





Main Goal

Develop algorithms for unsupervised unmixing of hyperspectral imagery



Geometry of Linear Mixing





Looking at Real Hyperspectral Imagery



- September, 2001 Fort A. P. Hill AVIRIS data collect
- Classification map derived using the PBSLv0 spectral library, see Cipar at al., 2004



Looking at Real Hyperspectral Imagery



Image chip from Fort AP Hill AVIRIS Image



Looking at Real Hyperspectral Imagery





- Image chip from Fort AP Hill AVIRIS Image
- First 2 PCs explain 97.5% of the total variability.
- First 4 PCs explain 99.2% of the total variability



Spatial Dependencies "Gravel Field"







Pixel info: (X, Y) Pixel Value



Spatial Dependencies "Grass Field"







Pixel info: (X, Y) Pixel Value



Spatial Dependencies "Vegetation"







Pixel info: (X, Y) Pixel Value



Spatial Dependencies: Simple Segmentation





Spatial Dependencies: Simple Segmentation





Spatial Dependencies: Simple Segmentation







- Global image data cloud is not the convex hull of a group of endmembers
 Materials mixing has a spatial dependency
 - Piecewise convex approximation (?)
- Convex regions in the global cloud → "local structure"



Proposed Idea





Simple Segmentation using Quadtree Partitioning



Goenaga-Jimenez, M.A, and Velez-Reyes, M., "Comparing Quadtree Region Partitioning Metrics for Hyperspectral Unmixing," Proc. SPIE 8743, 1219- 1228 (2013). http://cnx.org/contents/f0bdfbd9-ec2c-40ca-bb1ed7f025be17d9@4/Hyperspectral-imaging



Experiments with Fort AP Hill AVIRIS

- Comparison with published results
 Cipar et al. 2004
 - Spatial distributions of extracted abundances and reported information classes
- Comparison with cNMF applied to the entire image



Quad-Tree Image Partitioning of Fort AP Hill



Stopping Criterion:
Entropy of the tile is ≤ 90% of the total entropy, OR

 Tile size is 1/64 of the total image size.



+

Endmember Extraction with cNMF

$$(\hat{\mathbf{S}}_{p}, \hat{\mathbf{A}}_{p}) = \arg \min_{\substack{\mathbf{S}, \mathbf{A} \ge \mathbf{0} \\ \mathbf{A}^{T} \mathbf{1} \le \mathbf{1}}} \| \mathbf{X} - \mathbf{S}\mathbf{A} \|_{F}^{2}$$

$$\mathbf{X} \in \mathbb{R}^{m \times n}, \mathbf{S} \in \mathbb{R}^{m \times p}, \mathbf{A} \in \mathbb{R}^{p \times n}$$

+

Used only for endmember extraction. You can use your favorite method.



Endmembers per Tile

4		4	5	64	5	
		2	5	5 5		
4	4	3	5	5		3
4	3	4	5			
5	4	4	6	4	2	
5	3	3	5	4	4	3
5	4	5	4	5		4
3	5	6	5			

Knee of the Fitting Error Curve Used to Determine the Number of Endmembers

$$E_{p} = \frac{\left\| \mathbf{X} - \hat{\mathbf{A}}_{p} \hat{\mathbf{S}}_{p}^{T} \right\|_{F}}{\left\| \mathbf{X} \right\|_{F}}$$





Endmember Classes

- 181 Spectral Endmembers extracted
- Spectral endmembers were clustered in 11 Endmember Classes
 - Hierarchical clustering using complete linkage and angle distance
 - Davies-Bouldin validity index
 - clusterdata from MATLAB was used
- Image has 14 information classes in the classification map.



Experimental Results Fort AP Hill

Class Map Extracted sacNMF **Published** #1 summer 0.9 0.5 deciduous 0.8 forest 0.7 #2 0.6 loblolly 0.65 pine 250 0.5 0.55 zinn 0.4 0.45 0.3 #13 0.58 0.2 0.56 0.54 grass 0.52 field 0.1 0

50 100 150 200 250 300 350 400 450 500



0

Experimental Results Fort AP Hill

Published Class Map sacNMF **Extracted** 0.53 #10 0.52 100 150 0.51 generic 0.9 0.5 200 250 road 300 350 0.8 400 0.46 0.45 100 200 250 300 0.7 #11 0.6 river 200 250 water - 0.5 300 350 400 0.2 450 0. 0.4 50 100 150 200 250 300 350 400 450 500 0.3 0.58 #14 100 0.56 150 0.2 0.54 200 gravel 0.52 0.1 0.48 0.46 0.44

50 100 150 200 250 300 350 400 450 500



Experimental Results Fort AP Hill





Experimental Results Fort AP Hill

Extracted Published Class Map sacNMF 0.56 #9 100 0.54 0.9 150 soil ag 200 0.52 250 field #3 0.5 300 0.8 350 400 0.46 450 0.7 SÓ 0.44 200 250 300 350 400 450 500 160 0.63 - 0.6 0.6 0.58 ? 0.56 0.54 0.5 0.52 0.5 0.48 0.4 0.4 0.44 0.42 0.3 0.2

- - 0.1

0



Not Extracted







Green Ag Field #1



Soil Ag Field #1









Global cNMF Unmixing Results







0.46 0.44









- cNMF applied to the entire ۲ image
- Number of endmember • estimated using fitting error



Comparison with cNMF

cNMF



Vegetation





autumn deciduous #1

Proposed Approach



loblolly pine



autumn deciduous #2





green ag field #3



autumn deciduous #3



0.6

0.5

0.4

0.3

0.2

0.1



cNMF vs sacNMF

cNMF







Proposed Approach



river water













cNMF vs sacNMF

cNMF



Grass Field

Proposed Approach



Grass Field





Final Comments

- cNMF + Spatial partitioning
 - Facilitates extraction of endmembers capturing local spectral features.
 - Masked on the global cNMF approach
- Experimental results
 - Extracted endmember classes and abundances have good agreement with published ground truth.
- Other combinations possible
 - Tried superpixel segmentation with interesting results



Final Remarks

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