



Environmental Mapping & Analysis Program

Development Status and Future Plans

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2012 HyspIRI Science Workshop – Washington, DC

The EnMAP Program





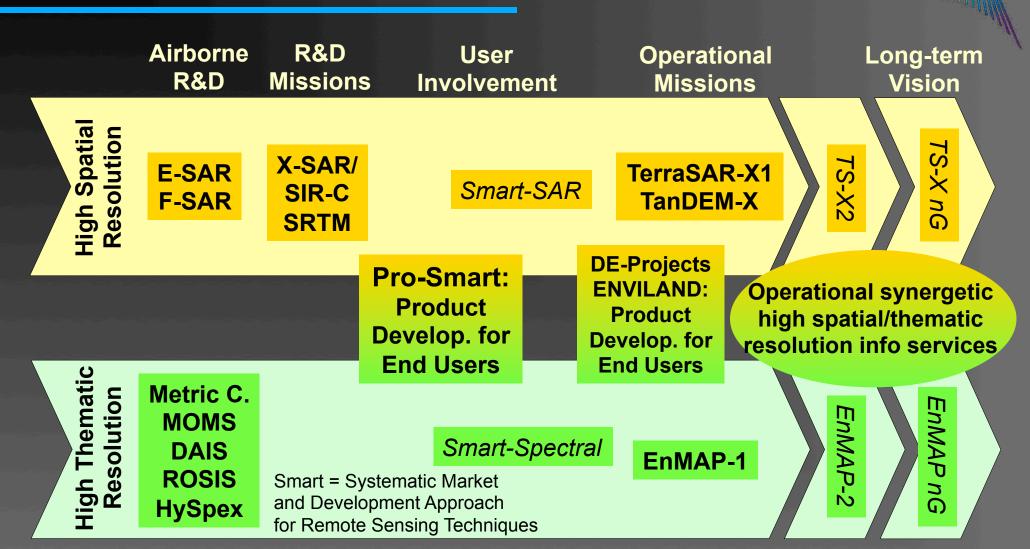
- EnMAP is Germany's first hyperspectral mission
- EnMAP is a scientific 'path finder mission' for later operational services
- It is funded by the Ministry of Economics and Technology





Overall German Programmatic Context







source: DLR-Agency



Project Partners















GFZ-Potsdam

Core Science Team **Advisory Board** **Project Management DLR Agency**

Space Segment Kayser-Threde - Spectrometer OHB Bremen - Bus Technology

Ground Segment DLR-Oberpfaffenhofen





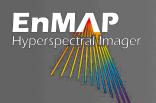








Overall Mission Goals



- To significantly contribute to environmental research studies, notably in the fields of ecosystem functions, natural resource management, natural hazards and Earth system modeling
- To provide high-spectral resolution observations of biogeochemical and geophysical variables on a global basis
- To develop new concepts and techniques for data extraction and assimilation to achieve synergies with other sensors
- To provide high-quality calibrated data and data products to be used as inputs for improved modeling and understanding of biospheric /geospheric processes

Science Plan downloadable from enmap.org in December





Terrestrial Ecosystems



Keywords: Ecosystem services, Biodiversity, Species migration, Precision farming, REDD, Urban growth

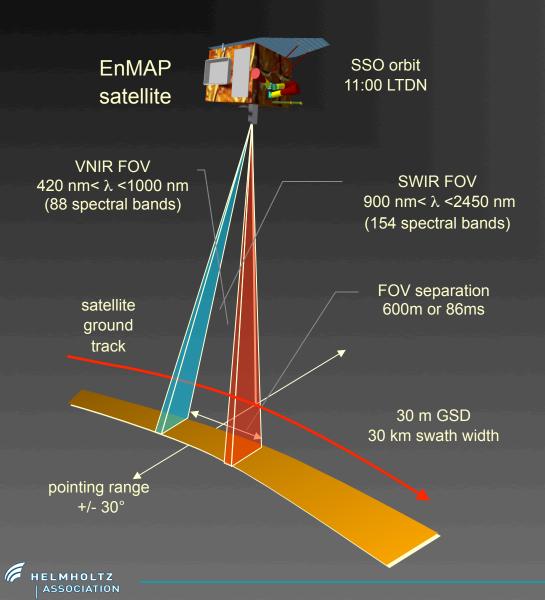
- Quantifying the impact of human activities such as land use/cover change, land management practices, and environmental pollution on ecosystems, their services and biodiversity.
- Quantifying the rate and consequences of ecosystem changes (e.g. species migration).
- Monitoring measures to combat biodiversity loss and improve ecosystem stability (e.g. REDD+).
- Assessing the impact of soot and dust on snow and glacial melt and the consequences for the hydrological cycle.
- Analysing the state and development of urban compositions and growth.





Main Mission Parameters





- Push-broom imager
- Spectral range:
 - 420 nm to 1000 nm (VNIR)
 - 900 nm to 2450 nm (SWIR)
- Spectral sampling distance:
 - VNIR 6.5 nm
 - SWIR 10 nm
- Total number of bands: 242
- Signal-to-noise ratio:
 - > 500 @ 495 nm
 - > 180 @ 2200 nm
- GSD at nadir: 30 m
- Swath width: 30 km
- Off-nadir pointing: ± 30°
- Mission lifetime: ≥ 5 years



Main Orbit Parameters



Near Nadir Global Coverage (± 5°)

Type: SSO-Near Repeat

Repeat Cycle: 23 days

Orbit height: 643.7 km

Eccentricity: 0.00113 ("Frozen")

Inclination: 97.96°

Orbital Period: 98 min

Inertial Axes

Repeat Rate: 4 days (± 30° tilt)

LTDN: 11:00 ± 15 min

Max. Length of Data Take: 1000 km / orbit 5000 km / day

tellite1

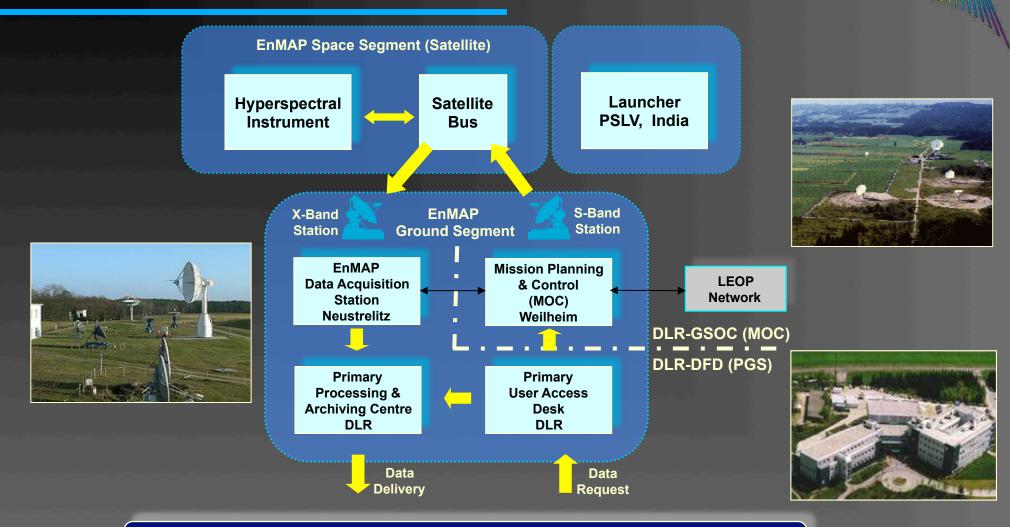
Time Step: 10.00 sec





Ground Segment





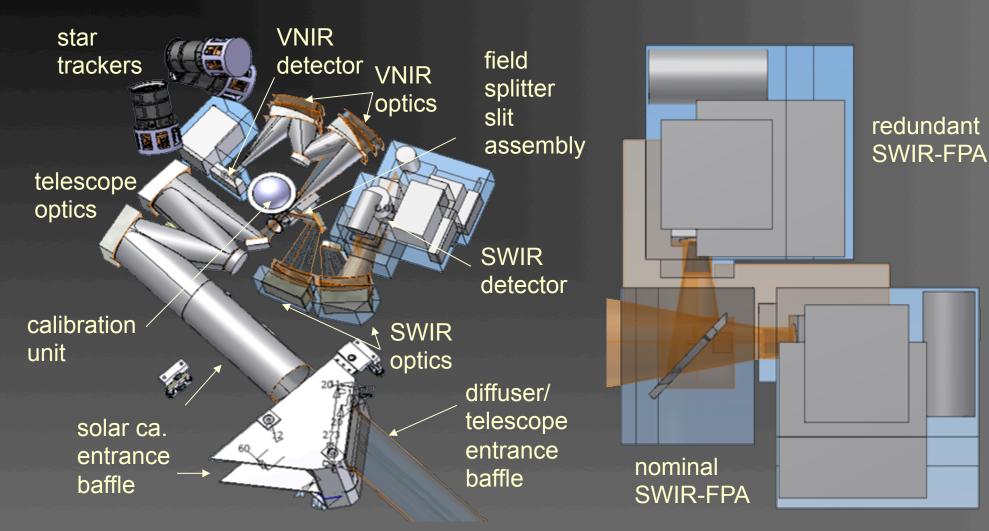
International EnMAP User Community





Instrument Optics Unit - Main Elements

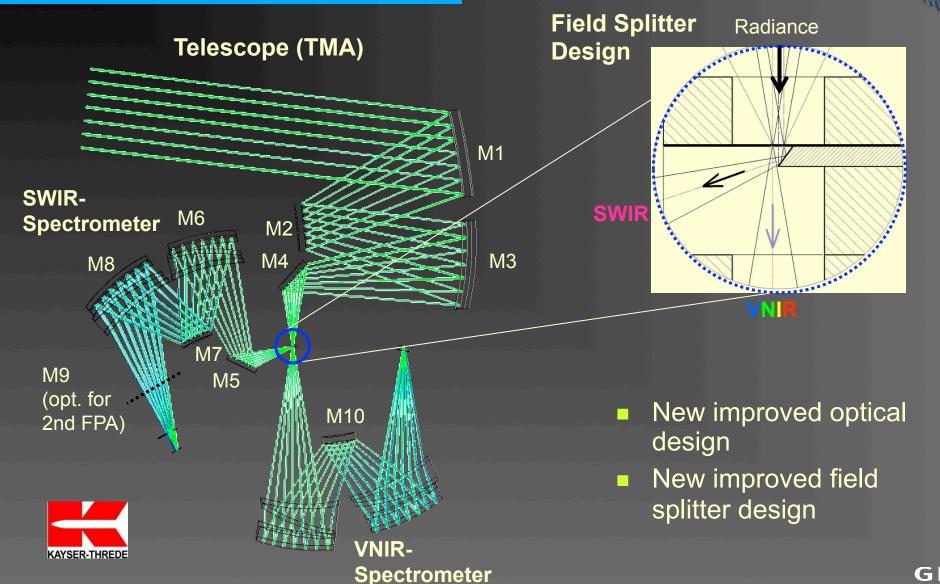




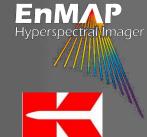


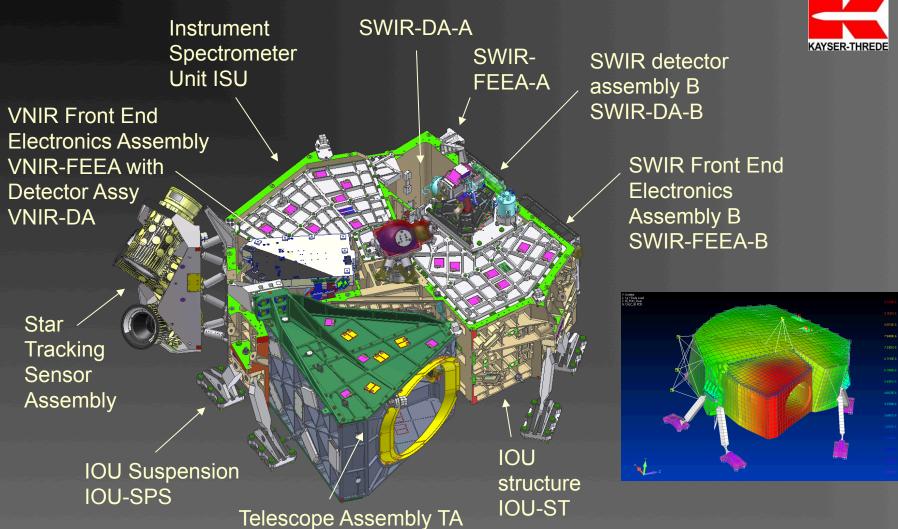
Optical System Layout





Instrument Design Status





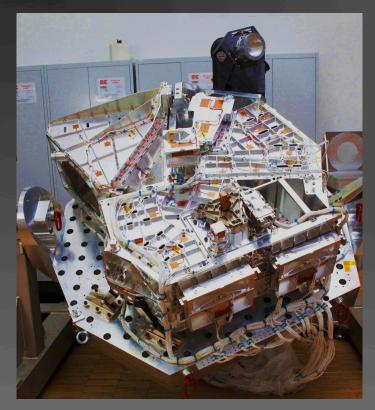


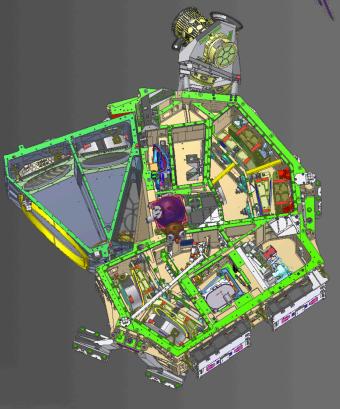


Satellite / Instrument – Bench and CAD





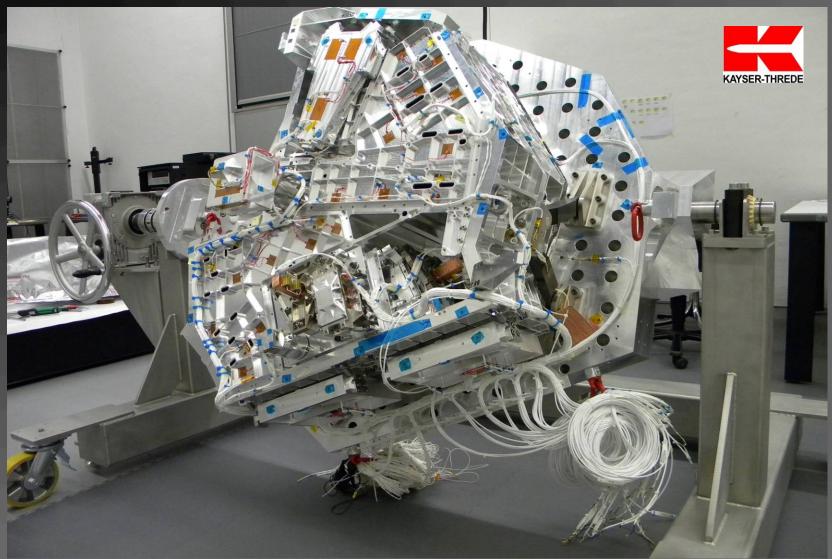






Instrument - Bench Clean Room







KT-Engineers / Vibration and Thermal Testing

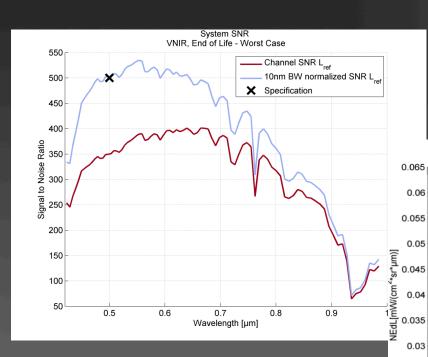




SNR / NEAL (VNIR)



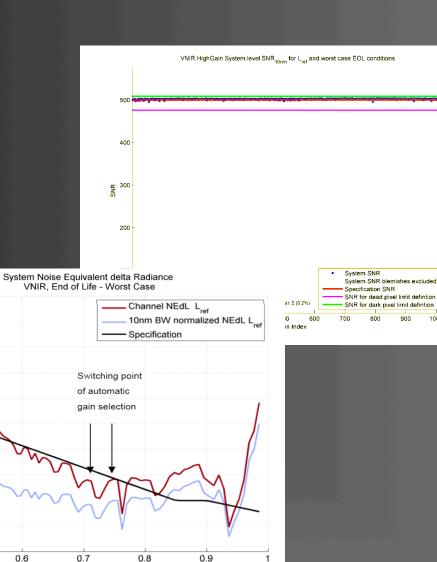
Performance simulation end of life worst case scenario



0.025 0.02 0.015

0.5

Wavelength [µm]



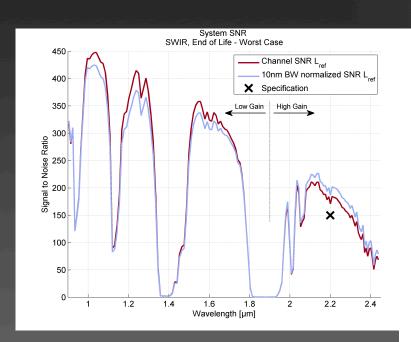


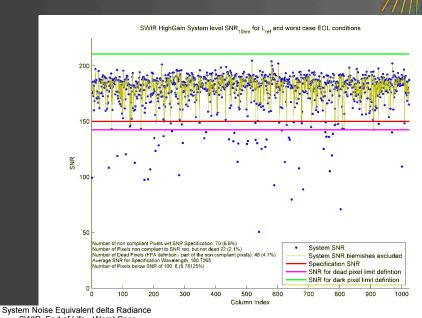


SNR / NEAL (SWIR)

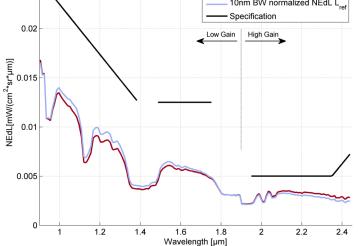


Performance simulation end of life (worst case scenario)









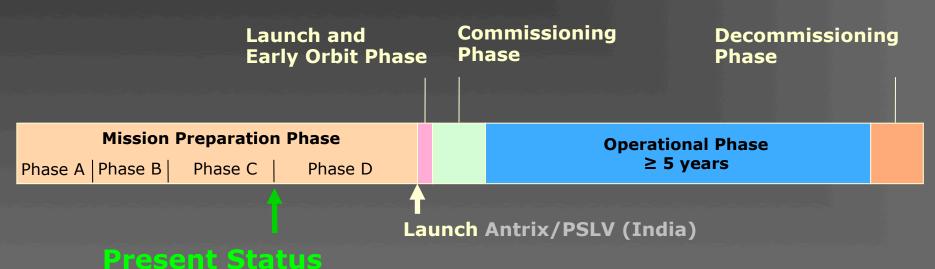


POTSDAM

History and Current Status

EnMAP
Hyperspectra Imager

- 2003 Submission of Proposal
- 2005 Phase A study accomplished
- 2007 Phase B accomplished
- 2008 Start of phase C/D
- 2010 CDR Ground Segment
- 2012 CDR Space Segment
- 2017/18 Launch







EnMAP End to End Simulator (Eetes)

EnMAP
Hyperspectral mager

Segl, K., Guanter, L., Rogass, C., Kuester, T., Roessner, S., Kaufmann, H., Sang, B., Mogulsky, V., and Hofer, S., (2012): EeteS—The EnMAP End-to-End Simulation Tool. *IEEE Journal*, **5/2**, 522-530.

Segl, K., Guanter, L., Kaufmann, H., Schubert, J., Kaiser, S., Sang, B., and Hofer, S., 2010, Simulation of spatial sensor characteristics in the context of the EnMAP hyperspectral mission. *IEEE-Transactions*, **48/7**, 3046-3054.

EnMAP Scene Simulator

Radiometric Module

Spectral Module

Spatial Module

Atmospheric Module

Input Data (Reflectance)

Onboard Calibration

Non-linearity

Dark Signal

Absolute Calibration

L1 Processor (DN->Radiance)

L2 Processors (Radiance->

Co-registration

Atmospheric Correction

Orthorectification

Output Data (Reflectance)



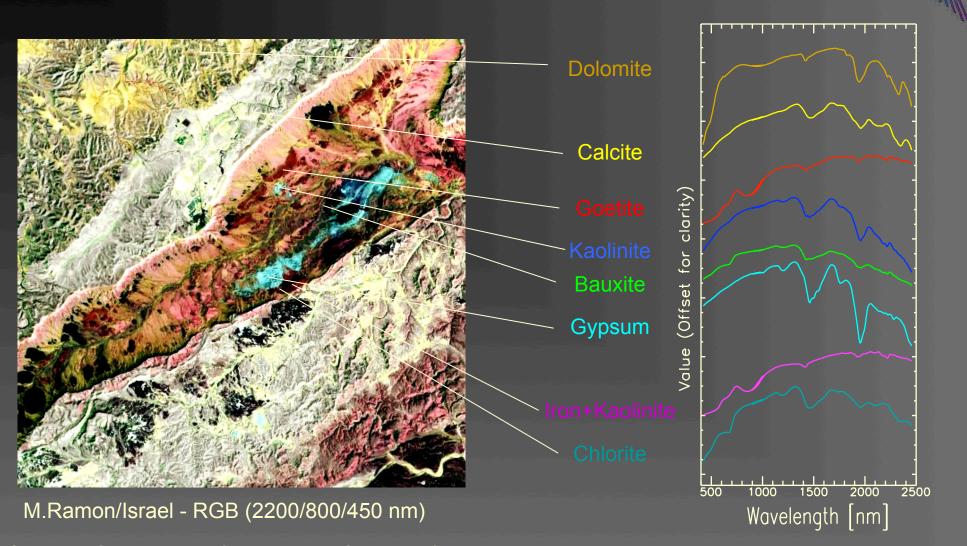


Simulation

-orward

Landscape Simulation





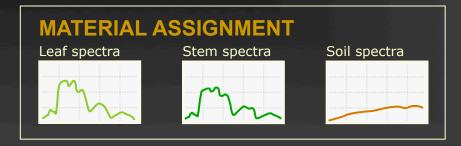
Guanter, L., Segl, K., and Kaufmann, H., 2009, Simulation of optical remote sensing scenes with application to the EnMAP hyperspectral mission. *IEEE-Transactions on Geoscience and Remote Sensing*, 47/7, 2340-2351.

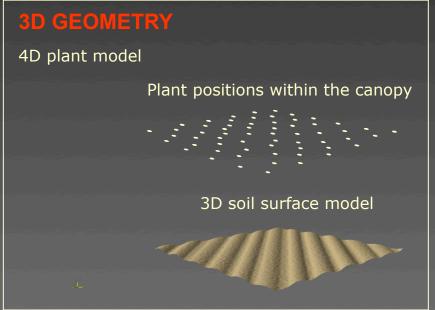
GFZ
Helmheltz Centre

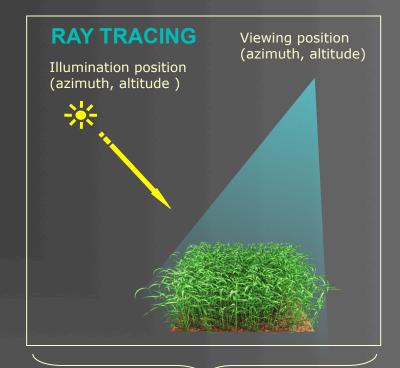


Correction Functions conc. BRDF Issues

- → Simulation of any canopy structure (e.g. row distance, plant density)
- → Simulation of each growth stage
- → Simulation of plant stress and disease







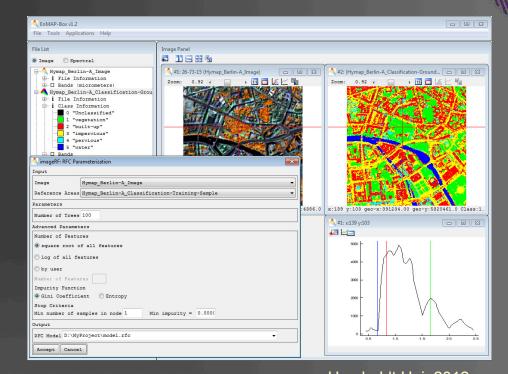


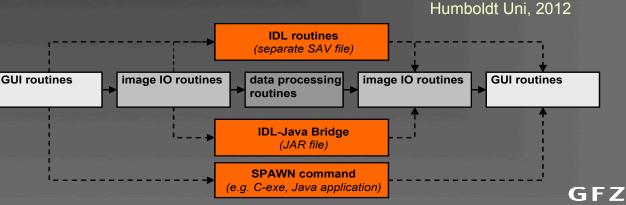




EnMAP Box

- Easy access to processing tools for hyperspectral data
 - widening user community
 - support for training courses
 - utability of state-of-the art algorithms
- Individual preprocessing tools for EnMAP data
- Platform to test and exchange new and innovative algorithms







POTSDAM

Primary Data Products



Product	Processor	Comment		
Level 0	Transcription	Stored in DIMS (no delivery)		
Level 1	Radiance	Processing on Demand; Meta Data updated for User Proc.		
Level 2geo	Georectification + Radiance	Geometric Correction		
Level 2atm	Co-Registration + Reflectance	Atmospheric Correction		
Level 2	Georectification + Co- Registration + Reflectance	Geometric and Atmospheric Correction		





Tasks – EnMAP Core Science Team (ECST)



TASKS		2010		2011		2012		
		J F M A M	1 J J A S O N D	J F M A M J J A S	O N D	J F M A	M J J	A S O N D
T 1	Science Plan & AO	(M1)	SP 1 M2	SP M3		M4)	SP3	(M5)
T 2	Summer Schools		(S1)	(S2)				S 3
T 3	Workshops	W1 W2	(W3)		W4			W5
T 4	Algorithms Development	A1 A2	(A3)	(A4)			(A5)	(A6)

Students Program 'Young EnMAP'

Task 1: Science Plan		
M1 M2 M3 M4 M5 SP1 SP2 SPF	ECST-Project Kick-Off 2. ECST Meeting ECST Mid-Term Meeting 4. ECST Meeting ECST Final Meeting Science Plan 1.Release Science Plan 2.Release Science Plan 3.Release	

Task 2: Summer Schools		
S1	Summer School 1 (Trier): Hyperspectral Data Exploitation	
S2	Summer School 2 (Munich): Algorithms & Field Campaigns (Cal/Val) Summer School 3 (Berlin):	
S3	International Pre-Launch Campaign	

Task 3: Workshops		
W1 W2 W3 W4 W5	Int. WorkshopHyperspectral 2010 (Frascati, Italy) Soil Workshop (GFZ) National Workshop 2010 (GFZ Potsdam) National Workshop 2011 (GFZ Potsdam)	

Task	4: Algorithms (Toolbox)	
A1 A2 A3 A4 A5 A6	Algorithmenauswahl Algorithm Priorisation Start Implementation End Implementation Start Beta Testing Toolbox Release & Dokumentation	



Fields of Cooperation



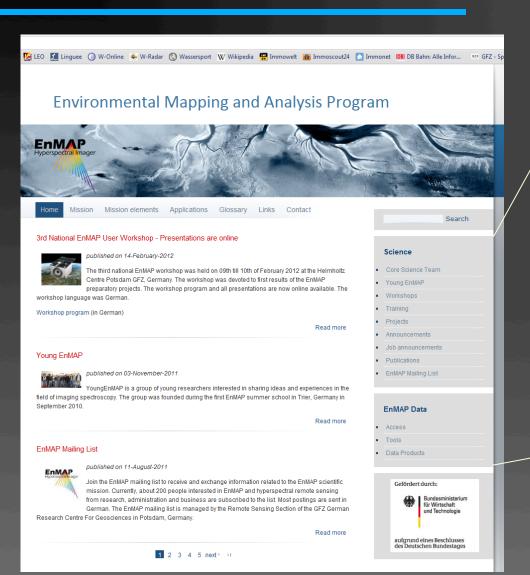
- Science case
- Exchange of students/postdocs
- Cal/Val
 - Vicarious calibration
 - Cross-calibration with HyspIRI, HISUI, Prisma, Hypxim, Shalom, others
- Software development
- Product generation (Toolbox)
- EnMAP-II development

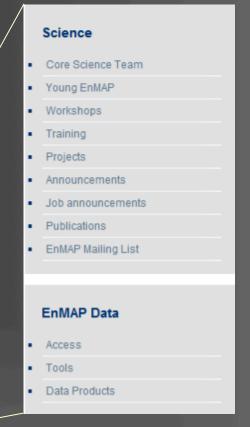




Gateway to EnMAP







http://www.enmap.org/ www.charly@gfz-potsdam.de

