

Prototyping Science As A Service with Intelligent Payload Module

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Team

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Geoff Bland – NASA/WFF – Cessna flights

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Vince Ambrosia - NASA/Ames – AMS instrument, B200/B100 flights, Ikhana

Steve Crago – ISI – Univ. of Southern Cal/ISI – Maestro onboard computer arch

Steve Chien – NASA/JPL – onboard algorithms

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Neil Shaw – NASA/GSFC summer intern

Joshua Bronston – NASA/GSFC co-op

Objectives

- Develop methods to provide low latency users of HyspIRI with quick look data products
- Augment concept of Science As A Service by providing an interface for nonprogrammer users to define new algorithms and select data sets and data feeds to run the algorithms against
- Virtualize the interface to various environments with adapters that take into account the resources and methods to expose key data and data products
- Experiment with high performance multicore space computing architectures in order to meet the future significantly higher data rates.
- Develop increasingly realistic operational architectures that emulate the target satellite architecture for HyspIRI and other Decadal missions

Funding for IPM Effort

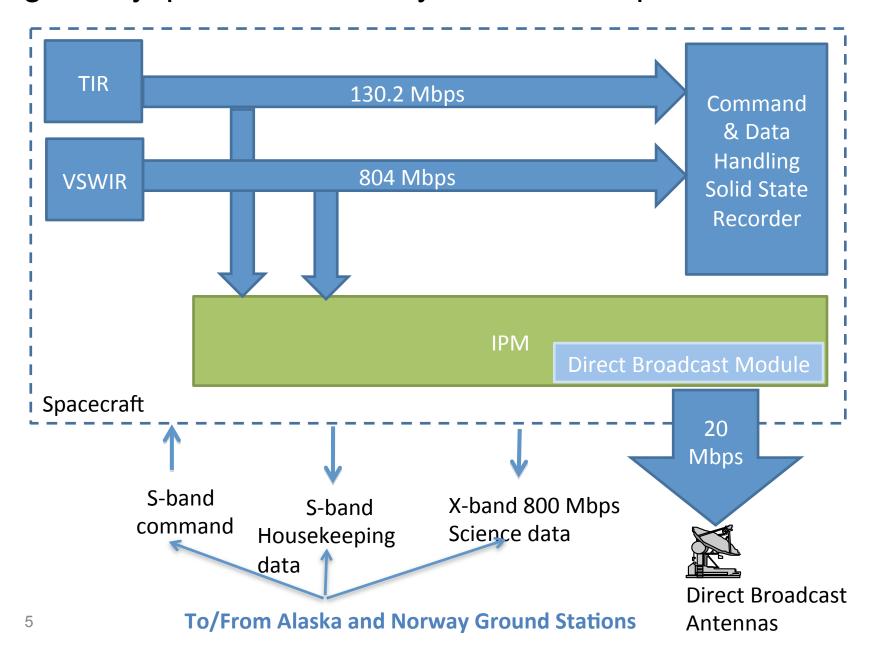
ESTO AIST-11 Award beginning May 2011

"A High Performance Onboard Multicore Intelligent Payload Module for Orbital and Suborbital Remote Sensing Missions"

GSFC IRAD FY 12:

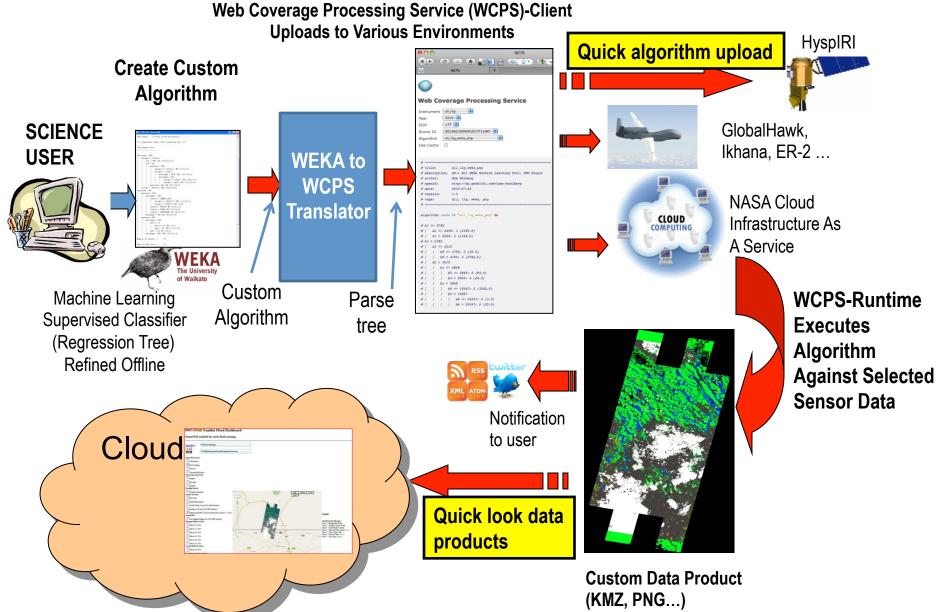
"Optimization of Onboard Processing Using the Maestro Multicore Processor for Decadal Missions" (Stepping stone to AIST award)

Original HyspIRI Low Latency Data Flow Operations Concept



Experimental IPM Quick Load/Quick Look Ops Con

Enhanced Ops Con from Baseline IPM Ops Con



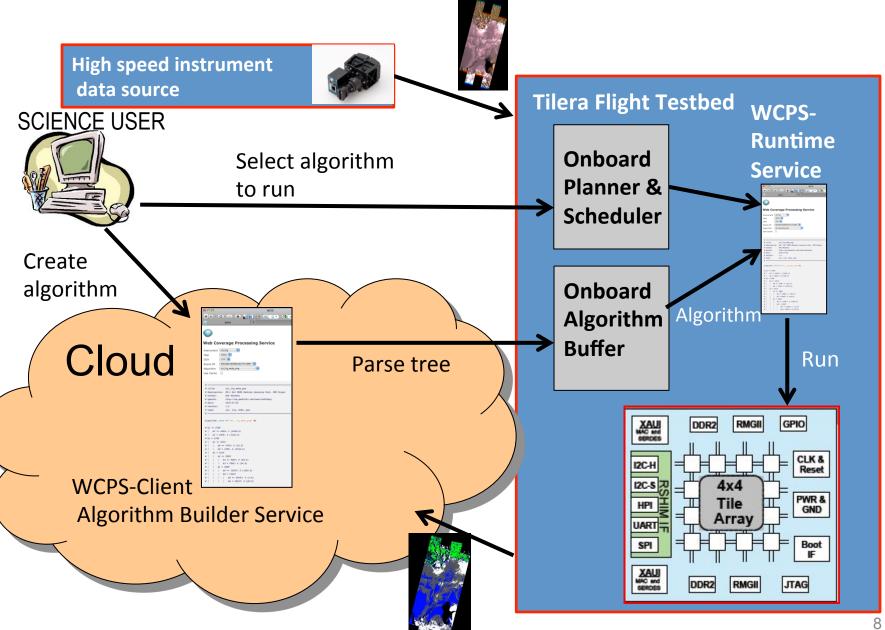
Roadmap for IPM Flight Opportunities

2020+ HyspIRI/HSI+ Thermal 2013-2014 2013-2014 2013-2014 Global Hawk Ikhana Maestro-lite Mini UAV Helicopter Instrument and IPM Configuration TBS 2012 2012 **AMS B200** ER-2 2012 **Spac**eCube Cessna **Space**Cube TileraPro TileraPro **Space**Cube 2008 Chai 640 TileraPro ISS

SpaceCube Xilinx FPGA

IPM Tilera Flight Testbed Ops Con

(Tilera board is proxy for Maestro and Maestro-lite)



Compact Hyperspectral Advanced Imager UV-VNIR

CHAI V-640

Compact and economical ideal for UAV and field use.



Chai640 Specs



The CHAI V-640 is the instrument of choice for applications requiring a compact, low-cost, and high-performance hyperspectral imager. The V-640 Integrates the most up-to-date Science CMOS Image sensors with a powerful Offner spectrometer to achieve excellent image quality with high sensitivity. The V-640 form factor is suitable for multi-unit arrangements, including side-by-side, fore- and aft-viewing angles, and varying polarizations.

APPLICATIONS

Earth Science, Aerial Survey, Machine Vision, Medical Imaging, Microscopy

ADVANTAGES

High Sansitivity, Lower Cost, Compact, Low Power

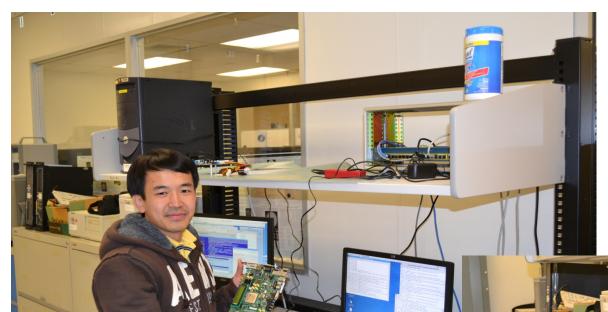
| MECHANICALS | ESTIMATE |
|----------------------------|-------------------------------------|
| Minimum Size | 127 x 101 x 51 mm |
| Weight | 1 kg sensor head 2 kg controller |
| Power | 40 watts |
| Temperature Range | -20 to +50 C |
| Size does not include lapt | op, processor or INS. |

| OPTICS | SPECIFICATION |
|-------------------------|--|
| Spectrometer Type | Offner |
| Field of View | 40 degrees (other upon request) |
| Cross Track Pixels | 640 (with BIN x3) |
| F-Number | f/2.8 |
| Data Rate | 78 Mbps |
| Spectral Range | 380-1000 nm |
| Smile | <0.1 pixels |
| Keystone | <0.1 pixels |
| Stray Light | <1e-4 Point Source Transmission |
| Spectral Bands | 256 |
| Spectral Sampling | 2.5, 5, 10 nm |
| Peak Grating Efficiency | 88% |
| Slit Size | 9.6 x .015 mm |
| IMAGE SENSOR | |
| Image Sensor | 1920 x 1080, 6.5 µm pixels |
| Well Depth | 30,000 electrons |
| Read Noise | 2 electrons |
| Maximum Frame Rate | 60 frames/second |
| Quantum Efficiency | 22% at 400 nm Peak 57% at 600 nm 15% at 900 nm |
| Camera Interface | CameraLink |
| Data Acquisition | 500 MB Solid State Recorder Serial Interface for GPS/INS |
| CHAI SOFTWARE | and the state of t |
| Trigger Modes | Pilot, GUI, electronic, and Lat/Long triggered acquisition |
| Visualization | 3-band RGB waterfall display of real-time and recorded data |
| Metadata | Temperature, pressure, and humidity |
| Data Format | RAW, ENVI BIL, or Processed |
| Processing | EXPRESSO" |

EXPRESSO to a technical of Shandywine Photonics (L.C.

^{*}Final product may differ from image shown.

IPM Testbed with Tilera Acting as Proxy for Maestro & Maestro-lite Board (building 23)



Above: Vuong Ly/583 (Ground System SW Branch) standing in front of IPM testbed holding a SpaceCube board.

Right: Tawanda Jacobs/582 (Flight SW Branch) working on integration of cFE onto IPM testbed.

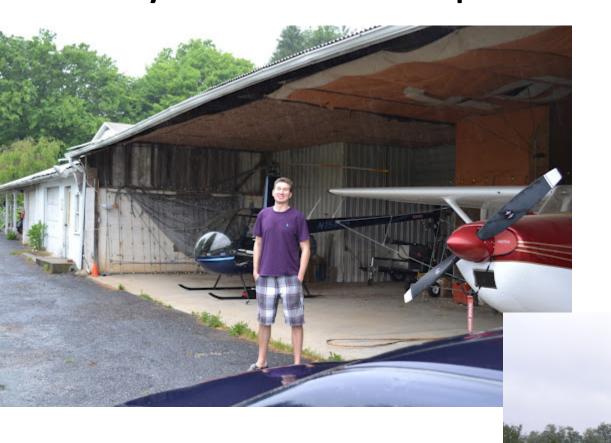
First Flight Opportunity Summer 2012



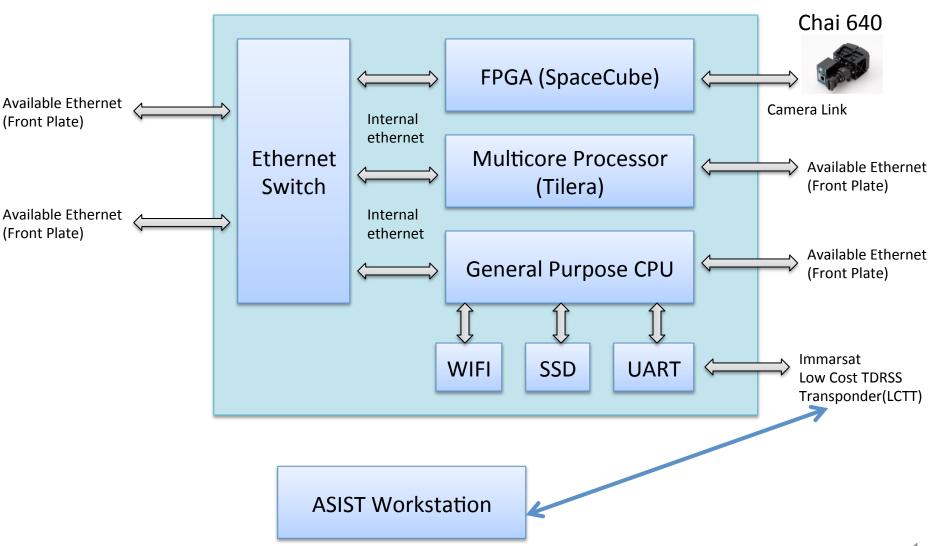
 Use Skycomp helicopter originating out Clarksville Maryland

- Land at GSFC
- Mount IPM
- Test on ground
- Test at various altitudes

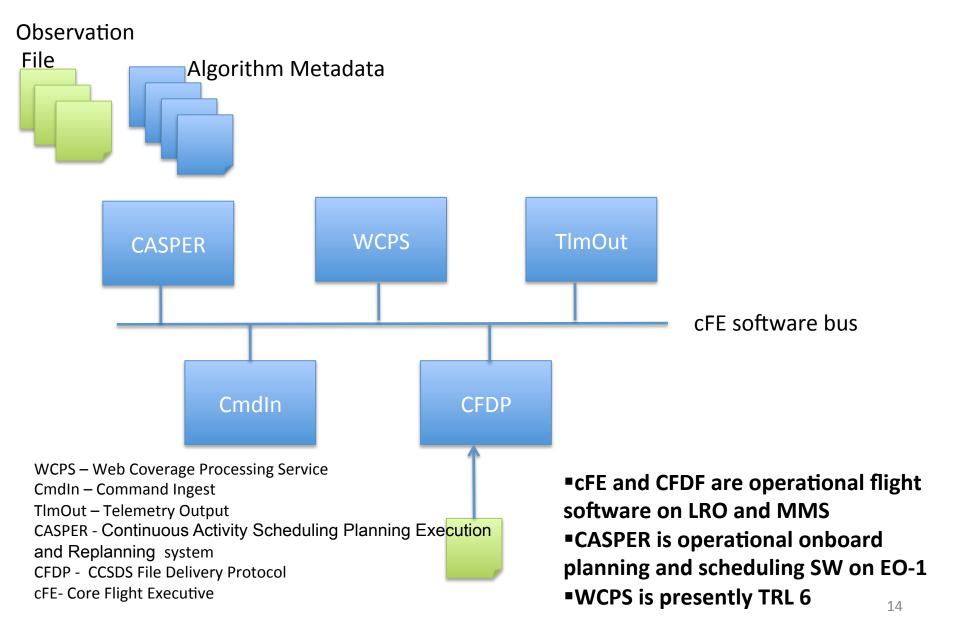
Hayesfield Airstrip in Clarksville, Md.



Target Hybrid Architecture



Preliminary Flight Architecture



Benchmarks for Use of Parallelization

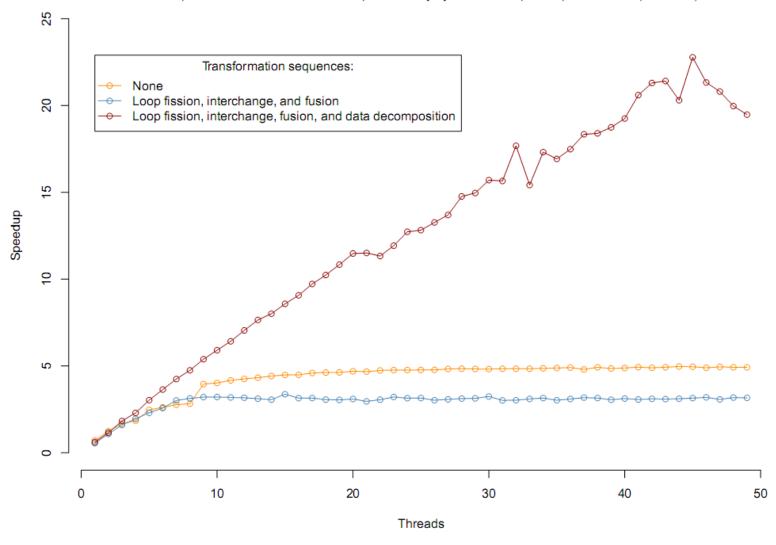


- Tim Creech, Univ. of Maryland, Phd student
 - NASA Science and Technology Research Fellowship (NSTRF) 3 year grant awardee
- Investigating methods to automatically transform algorithms into parallel processes that can be applied to multicore architectures
 - AESOP is software research area
 - Used algorithms running against EO-1 ALI data on Tilera testbed
- Working towards integrating automatic parallelization into WCPS

AESOP Parallelization Test Results (1 of 2)

AESOP - Speedups in Parallelized Spectral Angle Mapping on Tile64

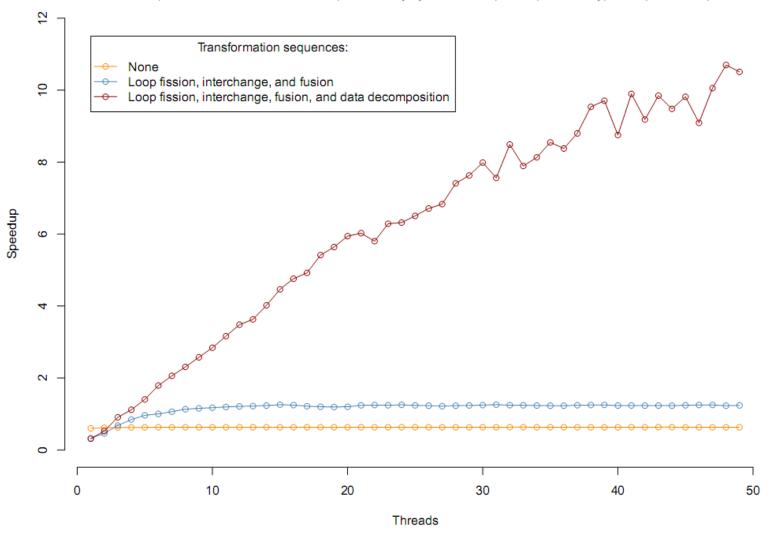
As compared to unmodified source compiled directly by Tilera's compiler. Input data: ALI (10 bands).



AESOP Parallelization Test Results (2 of 2)

AESOP - Speedups in Parallelized Spectral Angle Mapping on Tile64

As compared to unmodified source compiled directly by Tilera's compiler. Input data: Hyperion (220 bands).



Conclusion

- Develop methods to provide low latency users of HyspIRI with quick look data products
 - Showed efforts with Maestro/Tilera, SpaceCube, WCPS
- Augment concept of Science As A Service by providing infrastructure, interfaces and services for non-programmer users to define new algorithms and select data sets and data feeds to run the algorithms against selected data
 - Showed WCPS client to build algorithms in realtime and WCPS runtime to use as adapters in various environments to enable algorithms to run against selected data
- Virtualize the interface to various environments with adapters that take into account the resources and methods to expose key data and data products
 - - Showed WCPS runtime
- •Experiment with high performance multicore space computing architectures in order to meet the future significantly higher data rates.
 - - Showed a little of benchmarking to see how much performance can be enhanced with a multicore space computing architecture while designing in low power